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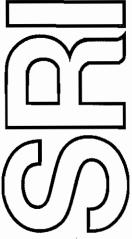
REASONING ABOUT PROGRAMS

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SRI Project 2245



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ABSTRACT

This paper describes a theorem prover that embodies knowledge about programming constructs, such as numbers, arrays, lists, and expressions. The program can reason about these concepts and is used as part of a program verification system that uses the Floyd-Naur explication of program semantics. It is implemented in the QA4 language; the QA4 system allows many pieces of strategic knowledge, each expressed as a small program, to be coordinated so that a program stands forward when it is relevant to the problem at hand. The language allows clear, concise representation of this sort of knowledge. The QA4 system also has special facilities for dealing with commutative functions, ordering relations, and equivalence relations; these features are heavily used in this deductive system. The program interrogates the user and asks his advice in the course of a proof. Verifications have been found for Hoare's FIND program, a real-number division algorithm, and some sort programs, as well as for many simpler algorithms. Additional theorems have been proved about a pattern matcher and a version of Robinson's unification algorithm. The appendix contains a complete, annotated listing of the deductive system and annotated traces of several of the deductions performed by the system.

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Problems worthy
of attack
Prove their worth
by hitting back.

Piet Hein

I INTRODUCTION AND BACKGROUND

This paper describes a computer program that proves theorems about programs. Proving theorems about programs is of practical importance because it helps certify that they are correct. Instead of testing a program on test cases, which may allow some bugs to remain, we can try to prove mathematically that it behaves as we expect. We hope future systems that reason about programs and understand how they work will help us to write and change programs.

Many programs have done this sort of reasoning. James King [1969]* developed a program verifier that could prove theorems about programs; his program proved an interesting class of theorems and was very fast. Peter Deutsch [1973] has recently written a system for interactive program writing that can also prove things about programs. It is perhaps not as fast as King's system, but it can prove more interesting theorems. S. Igarashi, R. London, and D. Luckham [1973] have recently applied a resolution theorem prover to program verification, and their results are impressive also. They can verify such programs as Hoare's [1961] FIND. Their system does little actual resolution and a lot of simplification and reasoning about equality. A program devised by Boyer and Moore [1973] can prove difficult theorems about LISP programs.

Thus, there is no shortage of interesting work related to our own.

The special characteristic of our own system is that it is markedly concise, readable, and easy to change and apply to new subject areas.

^{*}References are listed alphabetically at the end of the paper.

Our program verifier consists of a theorem prover (or deductive system) and a "verification condition generator." The verification condition takes an annotated program as input and constructs a list of theorems as output. The truth of the constructed theorems implies the correctness of the program. The task of the deductive system is to prove these theorems. The verification condition generator [Elspas et al., 1973] is written in BBN-LISP [Teitelman et al., 1971], and the deductive system is written in QA4 [Rulifson et al., 1972]. This paper focuses on the deductive system but, to be complete, gives examples of verification condition generation as well.

In writing our deductive system, we were motivated by several goals. First, the system should be able to find proofs; it should have enough deductive power to prove, within a comfortable time and space, the theorems being considered. Also, these proofs should be at the level of an informal demonstration in a mathematical textbook. This means that the difficulty in following one line to the next in any proof should be small enough that the proof is understandable, yet large enough not to be trivial. In any practical program verifier, the user will wish to follow the steps in a deduction. Who would believe a program verifier that only printed out "true" in the course of pursuing a proof? Furthermore, the strategies the system uses in searching for a proof should be strategies that we find natural. Not only should the tactics that eventually lead to the proof be ones we might use in proving the statement by hand, but also the false starts the system makes should be ones we might make ourselves. We do not want the system to rely on blind search; the trace of an attempted solution should make interesting reading.

In addition to the requirement that proofs be readable, the rules the system uses in going from one line to the next should be easy to read and understand. We should be able to look at a rule and see what

it does. Also, it should be easy to change old rules and to add new rules. The user of a program verifier is likely to introduce new concepts, such as operators or data structures. We want to be able to tell the deductive system how these structures behave and to have the system reason effectively using the new symbols. Giving the system new information should be possible without knowing how the system works, and certainly without reprogramming the system. Furthermore, the addition of new information should not prohibitively degrade the performance of the system.

The system is intended to evolve with use. As we apply the system to new problems, we are forced to give the system new information and, perhaps, to generalize some old information. These changes are incorporated into the system, which may then be better able to solve new problems.

Since the system is easy to extend and generalize, we do not worry about the completeness or generality of any particular version of the system. It is powerful enough to solve the sort of problem on which it has been trained, and it can be easily changed when necessary.

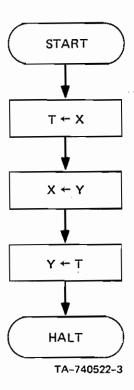
These considerations played a part in the design of the programming system called QA4, as well as in the construction of our deductive system, which is written in the QA4 language. Some of the techniques described below are embedded in the QA4 system itself; others are expressed as parts of the deductive system.

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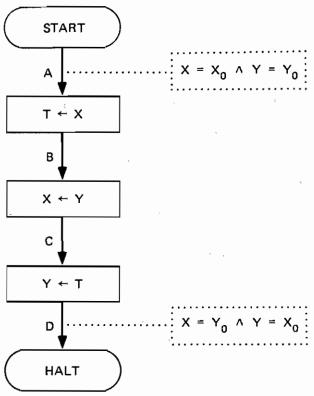
II THE FLOYD-NAUR METHOD

Perhaps not all readers are familiar with the method of proving statements about programs that we have followed in our work. Our method is a natural technique introduced independently by Floyd [1967] and Naur [1966] and formalized by Hoare [1969]. Knuth [1968] traces the germ of the idea back to von Neumann and Goldstine [1963] in the paper that introduced the concept of the flow chart. Although we cannot give a thorough introduction to that subject here, we provide below an example of its application to convey the flavor of the approach.

Consider a simple program that exchanges the values of two variables:



We assume that before the program is executed, X and Y have some initial values X_0 and Y_0 . Suppose we want to prove that after the program is executed, $X = Y_0$ and $Y = X_0$. We offer these <u>input</u> and <u>output</u> assertions as comments in our program:



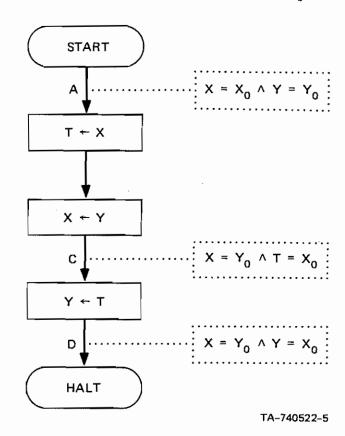
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These assertions are not to be executed by the program in any way, but they tell us something about the way the programmer expects his program to behave. He expects the assertion at A to be true when control passes through A, and the assertion at D to be true when control passes through D.

The essence of the Floyd-Naur approach is to generate from a commented program like the one above a set of statements called the verification conditions. If these statements are true, then the assertions the programmer has put in his program are correct. Whereas the programmer's assertions are correct only when control passes through the appropriate point, the verification conditions are true in general, and they can be

proved by a deductive system that knows nothing about sequential processing, loops, recursion, or other concepts about the flow of control and nothing else about the particular program.

To generate the verification condition for our sample program, we pass the output assertion back toward the input assertion. As we pass it back, we change it to reflect the changing state of the system. In particular, if any assignments are made within the program, then the corresponding substitution should be made in the assertion. Passing the assignment at D back to point C changes it to $X = Y_0$ and $T = X_0$:



We can argue that if the assertion at C is true when control passes through C, then the assertion at D will be true when control passes through D. In particular, if $T = X_0$ is true at C, and we execute $Y \leftarrow T$, then $Y = X_0$ will be true at D.

Passing the assertion all the way back to A in this manner gives the assertion Y = Y $_0$ \wedge X = X $_0$. If this assertion is true at A, then the final assertion will be true at D. However, we are already given the initial assertion X = X $_0$ \wedge Y = Y $_0$. The truth of the assertion at D then depends on the truth of the implication X = X $_0$ \wedge Y = Y $_0$ \supset Y = Y $_0$ \wedge X = X $_0$. This statement is the verification condition for this program. It can be proved by a deductive system independently of any knowledge about this program.

Constructing verification conditions by this method is an algorithmic process, not a heuristic one. Although the design of a language for expressing assertions remains an important and challenging problem (we introduce below some constructs for such a language), it is not a problem in the artificial intelligence domain. On the other hand, there is no cut and dried algorithm for proving verification conditions, and this is thus a fit subject for artificial intelligence research. Although we have no general algorithm for proving verification conditions, this somewhat restricted domain is more tractable than the general theorem-proving problem.

III A PROGRAM THAT FINDS THE LARGEST ELEMENT OF AN ARRAY

Before we explain how the system is structured or implemented, let us first look at a sample of some deductions performed by our system. This example will give a better idea of the subject domain of the inference system and of the sort of reasoning we have to do. It will also give a better picture of the process of generating a verification condition (Floyd [1967]).

Suppose we are given the annotated program shown in Figure 1 to compute the largest element in an array and its location. This program searches through the array, keeping track of the largest element it has seen so far and the location of this element. The intermediate assertion at C* says that MAX is the largest element in the array between 0 and I and that LOC is the index for MAX. Although our assertion language does not permit the ellipsis notation ("..."), we have introduced some suitable analogues, which are discussed later.

To prove assertions about a complex program, the system decomposes it into simple paths. This program can be decomposed into four simple paths:

- The path from B to C.
- The path from C to D.
- The path from C around the loop and back to C through point E.
- The path from C around the loop and back to C through point F.

^{*}In this program, and in examples throughout the paper, when we list several statements in an assertion, we mean the implicit conjunction of those statements. We will often also refer to each conjunct as an "assertion."

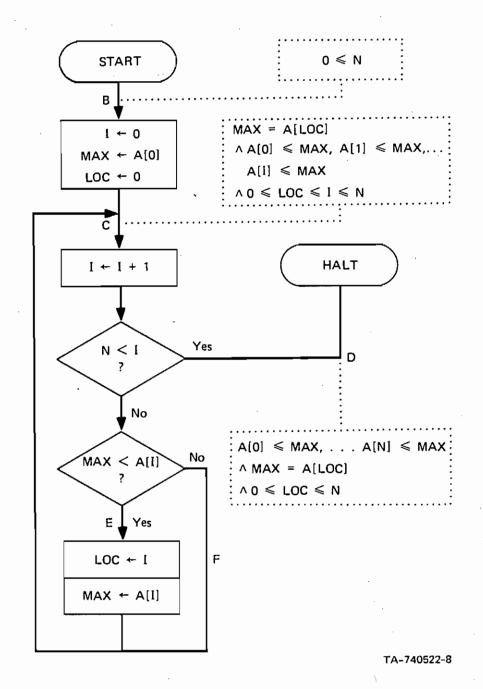


FIGURE 1 FINDING THE MAXIMUM OF AN ARRAY

Notice that the author of this program has put assertions not only at the START and HALT nodes of the program, but also at the intermediate point C. He has done this so that the proof of the program can be reduced to proving straight-line paths in the same way that the simple program of the previous section was verified. For instance, the path that begins at C, travels around the loop through E, and returns to C can be regarded as a simple, straight-line program with the assertion at C as both its start assertion and its halt assertion. The assertion at C has been cleverly chosen to be true when the loop is entered, to remain true whenever control travels around the loop and returns to C, and to be strong enough to allow the assertion at D to be proved when control leaves the loop and the program halts. (The choice of suitable internal assertions can be an intellectually exacting task; some heuristic methods have been proposed that will work in this and many other examples (Elspas et al. [1972], Wegbreit [1973], Katz and Manna [1973]).

If all the straight-line paths of the program are shown to be correctly described by the given assertions, and if the program can be shown to terminate (this must be done separately), then we can conclude that the program is indeed correct, at least with respect to the programmer's final assertion.

Although there are many paths in the decomposition of a program, typically most of the paths are easy to verify. For this program, we examine two of the paths.

First, suppose we want to demonstrate that if the assertion at point C is true when control passes through C, then the assertion at C will still be true if control passes around the loop and returns again to C. We will restrict our attention to the more interesting case, in which the test MAX < A[I]? is true; in this case, control passes through E. Furthermore, we will try to prove only that the second conjunct of the

assertion at C remains true. Our verification condition generator gives us the following statement to prove:

$$MAX = A\lceil LOC \rceil \land \tag{1}$$

$$A[0] \le MAX, \ldots, A[I] \le MAX \land \tag{2}$$

$$0 \le LOC \le I \le N \land \tag{3}$$

$$\neg (N < I+1) \land$$
 (4)

$$MAX < A[I+1] \supset$$
 (5)

$$A[0] \le A[I+1], \ldots, A[I+1] \le A[I+1]. \tag{6}$$

This statement is actually represented as five separate hypotheses and a goal to be deduced from these hypotheses. Lines (1) through (3) come from the assertion at C, and lines (4) and (5) come from the tests along the path. Line (6) comes from the assertion at C again. How the above statement is derived from the program is shown in detail in Appendix C.

The behavior of the deductive system in this problem is typical of its approach to many problems. The goal, (6), is broken into two subgoals:

$$A\lceil 0 \rceil \le A\lceil I+I \rceil \wedge \dots A\lceil I \rceil \le A\lceil I+I \rceil \tag{7}$$

and

$$A[I+1] \le A[I+1] \qquad . \tag{8}$$

The second subgoal, (8), is immediately seen to be true. The first subgoal, (7), is easily derived from (2) and (5).

Now let us look at the path from C to D. We will assume the assertion at C is true and will prove the assertion at D. We will look at the first conjunct of the assertion at D. Our verification condition generator gives us the following statement to prove:

$$MAX = A[LOC] \land \tag{9}$$

$$A \lceil 0 \rceil \leq MAX \wedge \ldots \wedge A \lceil I \rceil \leq MAX \wedge \tag{10}$$

$$0 \le LOC \le I \le N \land \tag{11}$$

$$N < I+1 \supset \tag{12}$$

$$A[0] \leq MAX \wedge \ldots \wedge A[N] \leq MAX \qquad . \tag{13}$$

The reasoning required for this proof is a little more subtle than the previous deduction. When the system learns that N < I+1 (12), it immediately concludes that N+1 \leq I+1, since N and I are integers. It further deduces that N \leq I. Since it already knows that I \leq N (11), it concludes that N = I. Using hypothesis (10), the system reduces the goal (13) to proving that I = N, which it now knows.

This deduction involves a lot of reasoning forward from assumptions and not much reasoning backward from goals. Both of these proofs are typical of the behavior of the system at large because of their strong use of the properties of equality and the ordering relations.

The QA4 system incorporates enough of the common techniques of theorem proving and problem solving that our inference system needs no general problem-solving knowledge, but only some knowledge about numbers, arrays, and other structures. The following sections show how the QA4 language allows that knowledge to be represented.

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IV THE QA4 LANGUAGE

A. Pattern Matching and the Goal Mechanism

The deductive system is made up of many rules expressed as small functions or programs. Each of these programs knows one fact and the use for that fact. The QA4 programming language is designed so that all these programs can be coordinated; when a problem is presented to the system, the functions that are relevant to the problem "stand forward" in the sense explained below.

A program has the form

(LAMBDA (pattern)(body))

Part of the knowledge of what the program can be used for is expressed in the pattern. When a function is applied to an argument, the pattern is matched against that argument. If the argument turns out to be an instance of the pattern, the match is said to be successful. The unbound variables in the pattern are then bound to the appropriate subexpressions of the argument, and the body of the program is evaluated with respect to those new bindings.

For example, the program

REVTUP = (LAMBDA (TUPLE $\leftarrow X \leftarrow Y$) (TUPLE \$Y \$X))

has pattern (TUPLE \leftarrow X \leftarrow Y) and body (TUPLE \$Y \$X). The prefix " \leftarrow " means that the variable is to be given a new binding. The prefix "\$" means that the variable's old binding is to be used. When REVTUP is applied to (TUPLE A B), the pattern (TUPLE \leftarrow X \leftarrow Y) is matched against (TUPLE A B). The match is seen to be successful, the variable X to be bound to A and the variable Y to be bound to B. The body (TUPLE \$Y \$X) is evaluated

with respect to these bindings, giving (TUPLE B A).

On the other hand, if a function is applied to an argument and the pattern of that function does not match the argument, a condition known as <u>failure</u> occurs. At many points in the execution of a program, the system makes an arbitrary choice between alternatives. Failure initiates a backing up to the most recent choice and the selection of another alternative. The mismatching of patterns is only one of the ways in which failure can occur in a program.

We have yet to explain how a program stands forward when it is relevant. In the above example, the function was called by name, much as it is in a conventional programming language. But it is also possible to make an argument available to any applicable program in a specified class. This is done by means of the goal mechanism.

When we say (GOAL (goalclass)(argument)), we assume that the goal class is a tuple of names of functions. We are making that argument available to the entire class of functions. The pattern of each of those functions is matched in turn against the argument. If the match is successful, the function is applied to that argument. If the function returns a value, that value is returned as the value of the goal statement. On the other hand, if a failure occurs in evaluating the function, backtracking occurs, the next function in the goal class is tried, and the process is repeated. If none of the functions in the goal class succeed, the entire goal statement fails.

For example, in our deductive system, one of the goal classes is called EQRULES, the rules used for proving equalities. One of these rules is

EQTIMESDIVIDE = (LAMBDA (EQ \leftarrow W (TIMES (DIVIDE \leftarrow X \leftarrow Y) \leftarrow Z))

(GOAL \$EQRULES

(EQ (TIMES \$Y \$W)(TIMES \$X \$Z))))

This rule states that to prove W = (X/Y)*Z, we should try to prove Y*W = X*Z. (The actual EQTIMESDIVIDE, shown in Appendix A, is more general than this.) The rule has the pattern

$$(EQ \leftarrow W (TIMES (DIVIDES \leftarrow X \leftarrow Y) \leftarrow Z))$$

If we execute (GOAL EQRULES (EQ A (TIMES (DIVIDES B C) D)) [i.e., we want to prove A = (B/C)*D, the system will try all the applicable EQRULES in turn. If none of the previous rules succeed, the system will eventually reach EQTIMESDIVIDE. It will find that the pattern of EQTIMESDIVIDE matches this argument, binding W to A, X to B, Y to C, and Z to D. Then it will evaluate the body of this function; i.e., it will try

If it fails to prove (EQ (TIMES A C)(TIMES B D)), it will try to apply the remaining EQRULES to the original argument, (EQ A (TIMES (DIVIDES B C) D)). The goal statement is an example of the pattern-directed function invocation introduced by Hewitt in PLANNER [1971].

The net effect of this mechanism is that it enables the user to write his programs in terms of what he wants done, without needing to specify how he wants to do it. Furthermore, at any point, he can add new rules to EQRULES or any other goal class, thus increasing the power of the system with little effort.

B. Some Sample Rules

The deductive system is a collection of rules represented as small programs. One rule was given in the preceding section; two more rules are presented here. The complete deductive system is included in Appendix A.

The first rule, EQSIMP, attempts to prove an equality by simplifying its arguments:

EQSIMP = (LAMBDA (EQ $\leftarrow X \leftarrow Y$)

(PROG (DECLARE)

(SETQ \leftarrow X (\$SIMPONE \$X))

(GOAL \$EQRULES (EQ \$X \$Y)))

BACKTRACK)

This rule says that to prove terms A and B are equal, simplify A and then prove that the simplified A is equal to B. This rule, a member of EQRULES, has the pattern (EQ \leftarrow X \leftarrow Y). SIMPONE, the simplifier, will fail if its argument cannot be simplified. In that case, EQSIMP will also fail. EQSIMP can actually simplify the right side of an equality, as well as the left, as explained in the Appendix A.

The second rule is

FSUBTRACTI = (LAMBDA (←F (SUBTRACT ←X ←Y) ←Z)

(GOAL \$INEQUALITIES

(\$F \$X (PLUS \$Y \$Z)))) .

This rule says that to prove X-Y \leq Z, try to prove X \leq Y+Z. It belongs to the goal class INEQUALITIES and is thus used not only for the predicate LTQ, but also for LT, GT, and GTQ. The variable F is bound to the appropriate predicate symbol.

C. <u>Demons</u>

The goal mechanism is used for reasoning backward from a goal. However, sometimes we want to reason forward from a statement. For example, suppose that whenever an assertion of the form X > Y is asserted, we want to assert $Y \le X$ as well. We do this by a QA4 mechanism known as the demon.

A demon is imagined to be a spirit that inhabits a hiding place, waiting until some specified event occurs, at which time it appears, performs some action, and vanishes again. We have put several demons in the

system, each watching for a different condition. For instance, one demon watches for statements of the form $X \geq Y$ and makes the statement $Y \leq X$. The user of the system can create his own demons. Demons are a tool for reasoning forward from an antecedent. In particular, we use demons to drive antecedents into a canonical form. For example, we drive all inequality expressions with integer arguments into an assertion of the form $X \leq Y$.

D. Representations

To as great an extent as possible, we have chosen representations that model the semantics of the concepts we use so as to make our deductions shorter and easier. For example, our language has data structures expecially intended to eliminate the need for certain inferences. In addition to tuples, which are like the familiar lists of the list-processing languages, we have the finite sets of conventional mathematics and bags, which are unordered tuples or, equivalently, sets that may have multiple occurrences of the same element. (Bags are called multisets by Knuth [1969], who outlines many of their properties.) Furthermore, we allow arbitrary expressions to have property lists in the same way that atoms can have property lists in LISP [McCarthy et al., 1962].

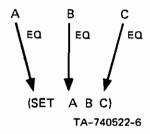
These data structures are useful in the modeling of equivalence relations, ordering relations, and arithmetic functions. For instance, if the addition of numbers and the multiplication of numbers are each rerepresented by a function of two arguments, then it becomes necessary to use numerous applications of the commutative and associative laws to prove anything about the number system. However, in QA4 all functions take only one argument, but this argument can be a tuple, set, or bag, as well as any other expression. Functions of multiple arguments can be represented by a function defined on tuples. However, a function that is commutative and associative, such as PLUS, is defined on bags. The

expression (PLUS A 2 B) really means (PLUS (BAG A 2 B)). Recall that bags are unordered; the system cannot distinguish between (BAG A 2 B) and (BAG 2 A B). Consequently, the expressions (PLUS A 2 B) and (PLUS 2 A B) are identically equal in our system. This makes the commutative law for addition redundant and, in fact, inexpressible in the language. Most needs for the associative law are also avoided.

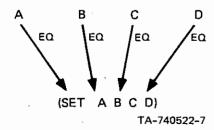
The logical function AND has the property that, for instance, (AND A A B) = (AND A B). The number of occurrences of an argument does not affect its value. Consequently, AND takes a set as its argument. Since (SET A A B) and (SET A B) are indistinguishable, (AND A A B) and (AND A B) are identical, and a statement of their equality is unnecessary. Some functions that take sets as arguments are AND, OR, EQ, and GCD (greatest common divisor).

When a new fact is asserted to our system, the value TRUE is placed on the property list of that fact. If at some later time we want to know if that fact is true, we simply look on its property list.

However, certain facts are given special handling in addition. For example, if we tell the system that certain expressions are equal, we form a set of those expressions. On the property list of each expression, we place a pointer to that set. For instance, if we assert (EQ A B C), the system stores the following:



If we subsequently discover any of these expressions to be equal to still another expression, the system adds the new expression to the previously formed set and puts the set on the property list of the new expression as well. For instance, if we assert (EQ B D), our structure is changed to the following:



The transitivity, symmetry, and reflexivity of equality are thus implicit in our representation. If we ask whether A and D are equal, the system knows immediately by looking at the property list of A or D.

Ordering relations are stored using the property list mechanism.

If we know that some expression A is less than B, we place a pointer to B on the property list of A:

$$A \xrightarrow{LT} B$$
 .

If we learn that B is less than C, we put a pointer to C on the property list of B:

$$A \xrightarrow{LT} B \xrightarrow{LT} C$$
 .

If we then ask the system if A is less than C, it will search along the pointers in the appropriate way to answer affirmatively. The transitive law is built into this representation.

The system knows about LT (<), GT (>), LTQ (\leq), GTQ (\geq), EQ (=), NEQ (\neq), and how these relations interact. For example, if we assert

 $X \ge Y$, $Y \ge Z$, and $X \le Z$, the system will know X = Y = Z and that (F X A) = (F Y A). Or if we assert $X \ge Y$ and $X \ne Y$, the system will know X > Y.

E. Contexts

When we are trying to prove an implication of the form $A \supset B$, it is natural to want to prove B under the hypothesis that A is true. Our assumption of the truth of A holds only as long as we are trying to prove B; after the proof of B is complete, we want to forget that we have assumed A. For this and other reasons, the QA4 language contains a context mechanism. All assertions are made with respect to a context, either implicitly or explicitly. For any context, we can create an arbitrary number of lower contexts.

A query made with respect to a context will have access to all assertions made with respect to higher contexts but not to any assertions made with respect to any other contexts. For instance, suppose we are trying to prove i < j \supset i + 1 \leq j with respect to some context C_0 . We may have already made some assertions in context C_0 . We establish a lower context, C_1 , and assert i < j with respect to C_1 . Then we try to prove i + 1 \leq j with respect to C_1 . When proving i + 1 \leq j, we know i < j, as well as all the assertions we knew previously in C_0 . When the proof of B is complete, we may have other statements to prove in C_0 . In doing these proofs, we will know all the assertions in C_0 and also, perhaps the assertion i < j \supset i + 1 \leq j, buy we will not know i < j because it was asserted with respect to a lower context.

F. User Interaction

Sometimes our rules ask us whether they should continue or fail.

This allows us to cut off lines of reasoning that we know in advance to be fruitless. If we make a mistake in answering the question, we may

cause the system to fail when it could have succeeded. However, we never cause the system to find a false or erroneous proof.

In addition to these mechanisms, which are built into the language processor, we have developed some notations that make it easier to discuss programming constructs; these notations are a part of our assertion language and are interpreted by the deductive system.

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V NOTATIONS

In speaking about the program to find the maximum element of an array, we found it convenient to use the ellipsis notation ("..."). We have not introduced this notation into our language; however, we have found ways of getting around its absence.

A. TUPA, SETA, BAGA

Let A be a one-dimensional array and I and J be integers. Then $(ext{TUPA A I J})$ is the tuple

If I > J, then (TUPA A I J) is the empty tuple.

(SETA A I J) and (BAGA A I J) are the corresponding bag and set. To state that an array is sorted between O and N, we assert

To state that an array A is the same in contents between O and N as the initial array ${\rm A}_{\rm O}$, although these contents may have been permuted, we assert

B. The STRIP Operator

Let X be a set or bag, $X = (SET \ X_1, \ldots, X_n)$, or $X = (BAG \ X_1, \ldots, X_n)$. Then (LTQ (STRIP X) Y) means $X_1 \le Y$ and $\ldots X_n \le Y$. For instance, to state that MAX is greater than or equal to any element in an array A between I and J, we assert

This is perhaps not quite as clear as

$$A[I] \le MAX$$
, $A[I+1] \le MAX$, ..., $A[J] \le MAX$

but we prefer it to

$$(\forall u) [I \le u \land u \le J) \supset A[u] \le MAX]$$

The STRIP operator is also used to remove parentheses from expressions:

is

We will eventually need two distinct operators, one to act as a quantifier and one to remove parentheses, but the single operator STRIP has played both roles so far.

C. ACCESS and CHANGE

Arrays cannot be treated as functions because their contents can be changed, wheras functions do not change their definitions. Thus, while f(x) is likely to mean the same thing for the same value of x at different times, A[x] is not. We overcome this difficulty by adopting McCarthy and Painter's [1967] functions ACCESS and CHANGE in our explication of the array concept:

- (ACCESS A I) means A[I].
- (CHANGE A I T) means the array A after the assignment statement $A[I] \leftarrow T$ has been executed.

We do not propose that ACCESS and CHANGE be used in writing programs or assertions; we do find that they make reasoning about arrays simpler, as

King suspected they would.

The next sections show examples of some fairly difficult proofs produced by the deductive system. The actual traces for some of these are included in Appendix B.

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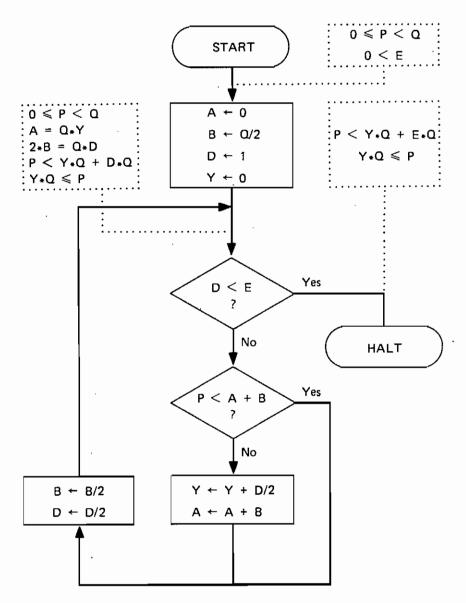
VI THE REAL NUMBER QUOTIENT ALGORITHM

Very little work has been done to prove properties of programs that work on the real numbers or the floating point numbers, although there is no reason to believe such proofs could not be done. Figure 2 shows, for instance, a program (Wensley [1958], Elspas et al. [1972]) to compute an approximate quotient Y of real numbers P and Q, where $0 \le P < Q$. This is an interesting and computationally plausible algorithm. It uses only addition, subtraction, and division by two, and it computes a new signigicant bit of the quotient with each iteration.

The algorithm can be understood in the following way. At the beginning of each iteration, P/Q belongs to the half-open interval [Y, Y+D). It is determined whether P/Q belongs to the left half or the right half of the interval. Y and D are adjusted so that in the new iteration, the half-interval to which Y belongs plays the role of the interval [Y, Y+D). Thus Y becomes a better and better approximation for P/Q.

We will consider here only one path through this program, i.e., the path around the loop that follows the right branch of the test P < A+B. We will prove only one loop assertion: P < Y*Q + D*Q. Our verification condition generator supplies us with the following hypotheses:

0 ≤ P ,	(14)
P < Q ,	(15)
A = Q*Y	(16)
2*B = Q*D , .	(17)
P < Y*Q + D*Q	(18)
$Y*Q \leq P$,	(19)
$\neg (D < E)$,	(20)



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FIGURE 2 THE WENSLEY DIVISION ALGORITHM

$$P < A+B \qquad . \tag{21}$$

The goal is to prove from these hypotheses that

$$P < Q*Y + Q*(D/2)$$
 (22)

These hypotheses and the goal were constructed in a manner precisely analogous to the generation of the condition for the previous example of computing the maximum of an array.

The proof goes as follows. After an abortive attempt at using the assertion (18), the system tries to show that the conclusion follows from (21). It therefore tries to show that

$$A+B \le Q*Y + Q*(D/2)$$
 . (23)

This goal is broken into the following two:

$$A \leq Q*Y \tag{24}$$

$$B \le Q*(D/2) \tag{25}$$

Of course, this strategy will not always be successful. However, in this case goal (24) follows from (16), whereas (25) reduces to (17).

A complete trace of this proof and listings of the rules required to achieve it are provided in Appendices A and B.

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VII A PATTERN MATCHER

As an experiment in the incorporation of new knowledge into the system, we performed the partial verification of a simple pattern matcher and a recursive version of the unification algorithm [Robinson, 1965]. These algorithms were of special interest to us because they involve concepts we have actually used in the implementation of the QA4 program itself. They are thus in some sense realistic, although neither of these programs appears literally in the QA4 code. The subject domain is as follows.

We assume that <u>expressions</u> are LISP S-expressions [McCarthy, 1962]; for example, (F X (G A B)) is an expression. Atomic elements are designated as either <u>constant</u> or <u>variable</u>, and they can be distinguished by the use of the predicates const and var. Here we use A, B, C, F, and G as constants and U, V, W, X, Y, and Z as variables:

- var(X) is true
- const(A) is true
- var(A) is false
- var((X Y)) is false.

A <u>substitution</u> replaces some of the variables of an expression by terms. Substitutions are represented as lists of dotted pairs. (($X \cdot A$) ($Y \cdot (F \cdot G)$) is a substitution. Varsubst(s,e) is the result of making substitutions in expression e. If s is

$$((X \cdot A) (Y \cdot (G B)))$$
,

and e is

(F X A (Y B))

then varsubst(s,e) is

The LISP functions car, cdr, list, and atom can be used to manipulate expressions. The empty substitution is denoted by EMPTY and has no effect on an expression. An operation called compose, the composition of substitutions, defined by Robinson [1965], has the following property:

varsubst(compose(s1, s2), e) = varsubst(s1, varsubst(s2, e))

The problem of pattern matching is defined as follows: Given two expressions called the pattern and the argument, try to find a substitution for the variables of the pattern that makes it identical to the argument. We call such a substitution a <u>match</u>. For example, if the pattern is

and the argument is

then match(pat, arg) is

$$((X \cdot D) (Y \cdot C))$$
.

If there is no substitution that makes the pattern identical to the argument, we want the pattern matcher to return the distinguished atom NOMATCH. Thus, if pat is $(X \ Y \ X)$ and arg is $(A \ B \ C)$, then match(pat, arg) = NOMATCH, since we cannot expect X to be matched against both A and C.

For simplicity, we assume that the argument contains no variables.

A LISP-like program to perform the match might be

```
match(pat, arg) = prog ((ml m2)
  if const(pat) then (if pat = arg then
    return(EMPTY) else return(NOMATCH))
  if var(pat) then return(list (cons(pat, arg)))
  if atom(arg) then return(NOMATCH)
  ml \( \therefore\) match(car(pat), car(arg))
  if ml = NOMATCH then return(NOMATCH)
  m2 \( \therefore\) match(varsubst(ml, cdr(pat)), cdr(arg))
  if m2 = NOMATCH then return(NOMATCH)
  return(compose (m2, ml)) .
```

The program does the appropriate thing in the case of atomic patterns or arguments, and it calls itself recursively on the left and right halves of the expressions in the nonatomic case. The program applies the substitution found in matching the left halves of the expressions to the right half of the pattern before it is matched so as to avoid having the same variable matched against different terms.

We have proved several facts about a version of this program, but we focus our attention here on one of them: If the program does not return MOMATCH, then the substitution it finds actually is a match; i.e., that applying the substitution to the pattern makes that pattern identical to the argument. Thus, the output assertion is:

```
match(pat, arg) ≠ NOMATCH ⊃
varsubst(match(pat, arg), pat) = arg
```

Since we assume the argument contains no variables, the input assertion is

We have verified one condition for the longest path of <u>match</u> with respect to these assertions. This path is followed when the pattern and the argument are both nonatomic and when the recursive calls on <u>match</u> successfully return a substitution. In writing our verification condition, we use the same abbreviations the program does, i.e.,

and

In proving a property of a recursively defined program, we follow Manna and Pnueli [1970] and assume that property about the recursive call to the program. Thus, for this program we have the inductive hypotheses

constexp(car(arg))
$$\land$$
 m2 \neq NOMATCH \supset varsubst(m1, car(pat)) = car(arg)

(the program works for the car of the pattern) and

$$constexp(cdr(arg)) \land m2 \neq NOMATCH \supset$$

$$varsubst(m2, varsubst(m1, cdr(pat))) = cdr(arg) . (28)$$

(the program works for the instantiated cdr of the pattern). The verification condition generator would split both of these hypotheses into three cases; we will consider only the case in which the antecedents of both implications are ture. Hence, we assume that both the recursive calls to the pattern matcher succeed in finding matches.

By the path we have taken through the program, we know that

$$\neg const(pat)$$
 (29)

(the pattern is not a constant).

$$\neg var(pat)$$
 (30)

(the pattern is not a variable).

$$-$$
 atom(arg) (31)

(the argument is not an atom). Since for this path

the goal is to prove

$$varsubst(compose(m2, m1), pat) = arg$$
 (32)

The proof produced by the system proceeds as follows. The goal is split into two subgoals:

$$varsubst(compose(m2, m1), car(pat)) = car(arg)$$
 (33)

and

$$varsubst(compose(m2, m1), cdr(pat)) = cdr(arg)$$
 . (34)

From the property of "compose," the first goal is simplified to

Since

by (27), this simplifies to

$$varsubst(m2, car(arg)) = car(arg)$$

Since arg contains no variables, neither does car(arg). Thus, the goal simplifies to

$$car(arg) = car(arg)$$
.

The proof of (34) is even simpler:

simplifies to

We know by our hypothesis (28) that

and this completes the proof.

This proof required not only that we add new rules describing the

concepts involved, but also that we extend certain of our older capabilities, particularly our ability to simplify expressions using known equalities. A complete trace of the proof is included in Appendix B.

We worked nearly a week before the system was able to do this proof. However, once the proof was completed, the effort necessary to enable the system to do the proof of the unification algorithm was minimal. The latter proof, though longer than this one, did not require much additional intellectual capacity on the part of the deductive system. We do not show that proof here because it is similar to the pattern matcher proof, but we include the program and the assertion we proved about it.

VIII THE UNIFICATION ALGORITHM

The problem of unification is similar to that of pattern matching except that we allow both arguments to contain variables. We expect the algorithm to find a substitution that makes the two arguments identical when it is applied to both, if such a substitution exists. For example, if x is (F U A) and y is (F B V), then unify(x, y) is ((U•B)(V•A)), where U and V are variables and A, B, and F are constants.

A simple program to unify x and y is

```
unify(x, y) = prog((ml m2))
  if x = y then return(EMPTY)
  if var(x) then
    return(if occursin(x, y) then NOMATCH
                              else list (cons(x, y)))
  if var(y) then
    return(if occursin(y, x) then NOMATCH
                              else list (cons(y, x)))
  if atom(x) then return(NOMATCH)
  if atom(y) then return(NOMATCH)
  ml \leftarrow unify(car(x), car(y))
  if m1 = NOMATCH then return(NOMATCH)
  m2 \leftarrow unify(varsubst(ml, cdr(x)),
             varsubst(ml, cdr(y)))
  if m2 = NOMATCH then return(NOMATCH)
  return(compose(m2, m1)))
```

The predicate occursin(u,v) tests if u occurs in v. This program is a recursive, list-oriented version of Robinson's iterative, string-oriented program. Again, we have verified only the longest path of the program, not the entire program. Furthermore, we have proved not the strongest possible statement about this program, but only that

```
unify(x,y) \neq NOMATCH \supset varsubst(unify(x,y), x) = varsubst(unify(x,y), y)
```

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IX THE FIND PROGRAM

The program FIND, described by Hoare [1961] is intended to rearrange an array A so that all the elements to the left of a certain index F are less than or equal to A[F], and all those to the right of F are greater than or equal to A[F]. In other words, the relation (STRIP (BAGA A 1 F-1)) \leq A[F] \leq (STRIP (BAGA A F+1, NN)) should hold when the program halts. For instance, if F is NN÷2, then A[F] is the median of the array. The function is useful in computing percentiles and is fairly complex.

Hoare remarks that a sorting program would achieve the same purpose but would usually require much more time; the conditions for FIND are much weaker in that, for example, the elements to the left of F need not be sorted themselves, as long as none of them are greater than AFF].

The ALGOL representation of FIND is as follows:

```
BEGIN
       INTEGER M, N;
       M \leftarrow 1;
       N \leftarrow NN;
       WHILE M < N DO
              BEGIN INTEGER R, I, J;
                     R \leftarrow A[F];
                     I \leftarrow M;
                     J \leftarrow N;
                     WHILE I \leq J DO
                     BEGIN WHILE A[I] < R DO I \leftarrow I+1;
                             WHILE R < A[J] DO J \leftarrow J-1;
                             IF I \leq J THEN
                             BEGIN EXCHANGE (A I J)
                                    I \leftarrow I+1
                                    J \leftarrow J-1
                             END
                     END
                     IF F \leq J THEN N \leftarrow J
                     ELSE IF I \leq F THEN M \leftarrow I
                             ELSE GO TO L
              END
       L:
END
```

The general strategy of the program FIND is to move "small" elements to the left and "large" elements to the right. These relative size categories are defined as being less than or not less than an arbitrary array element. The algorithm scans the array from left to right looking for a large element; when it finds one, it scans from right to left looking for a small element. When it finds one, it exchanges the large element and the small element it has already found, and the scan from the left continues where it left off until the next large element is found, and so on. When the scan from the left and the scan from the right meet somewhere in the middle, they define a split in the array. We can then show that all the elements to the left of the split are small and all those to the right are large.

The index F can be either to the left or to the right of the split, but suppose it is to the left. Then the elements to the right of the split can remain where they are; they are the largest elements in the array, and the element that will ultimately be in position F is to the left of the split. We then disregard the right portion of the array and repeat the process with the split as the upper bound of the array and with a refined definition of "large" and "small." We will eventually find a new split; suppose this split is to the left of F. We can then leave in place the elements of the array to the left of the split and work only with the elements to the right; we readjust the left bound of the array to occur at the split, and we repeat the process. Thus, the left and right bounds of the array move closer and closer together, but they always have F between them. Finally, they meet at F, and the algorithm halts.

The flow chart in Figure 3 follows Hoare's algorithm closely.

In this program, I is the pointer for the left-to-right scan, J is the pointer for the right-to-left scan, M and N are the lower and upper bounds of the "middle" portion of the array, and R is the value used to discriminate between small and large array elements. Hoare [1971] provided an informal manual proof of the correctness of his program. Igarashi, London, and Luckham [1973] have produced machine proofs. The proof we obtained required a minimal number (three) of intermediate assertions; however, one of the verification conditions produced was quite difficult to prove. This condition corresponds to the statement that the elements to the right of the right boundary dominate the elements to its left after an exchange is performed and a new right boundary is established. We present a sketch of that proof below.

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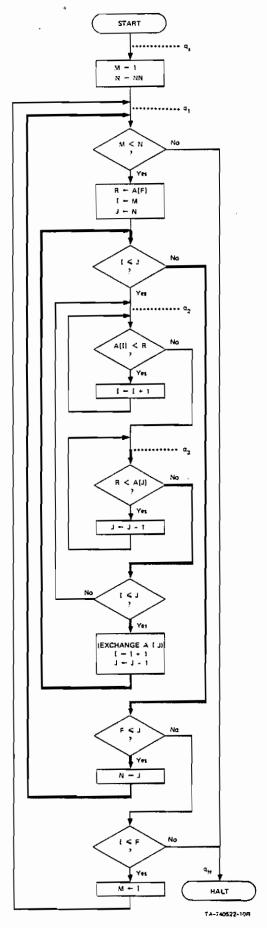


FIGURE 3 THE FIND PROGRAM

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A. Assertions for FIND

The input assertion q for FIND is (the conjunction of)

$$1 \le F \le NN$$
, $A = AP$,

The array AP is the initial version of A; we define it in the input assertion so that we can refer to it after we have modified A.

The output assertion q_H is

```
(STRIP (BAGA A 1 F-1)) \leq A[F] \leq (STRIP (BAGA A F+1, NN)) (BAGA A 1 NN) = (BAGA AP 1 NN) .
```

The second conjunct of q_H states that when the program terminates, the array A is indeed a permutation of the initial array AP.

The intermediate assertion q_1 is

```
1 \le M \le F \le N \le NN
(STRIP (BAGA A 1 M-1)) \le (STRIP (BAGA A M NN))
(STRIP (BAGA A 1 N)) \le (STRIP (BAGA A N+1 NN))
(BAGA A 1 NN) = (BAGA AP 1 NN)
```

This assertion is reached whenever a new bound on the middle section of the array is established.

The assertion q_2 is

```
1 \le M \le F \le N \le NN (STRIP (BAGA A M NN)) (STRIP (BAGA A 1 M-1)) \le (STRIP (BAGA A M NN)) (STRIP (BAGA A 1 N)) \le (STRIP (BAGA A N+1 NN)) M \le I J \le N (STRIP (BAGA A 1 I-1)) \le R \le (STRIP (BAGA A J+1 NN)) (BAGA A 1 NN) = (BAGA AP 1 NN) .
```

The assertion $\mathbf{q}_{\mathbf{3}}$ is the same as the assertion $\mathbf{q}_{\mathbf{2}},$ with the additional conjunct

$$R \leq A \Gamma I$$
.

B. The Proof

All but one of the verification conditions for this program were proved fairly easily. The one difficult condition corresponds to the path beginning at \mathbf{q}_3 that follows the heavy line and finally ends at \mathbf{q}_1 . The verification condition generator supplied us with the following hypotheses:

$1 \leq M \leq F \leq N \leq NN$	(35)
(STRIP (BAGA A 1 M-1)) ≤ (STRIP (BAGA A M NN))	(36)
(STRIP (BAGA A 1 N)) \leq (STRIP(BAGA A N+1 NN))	(37)
$M \leq I$	(38)
$J \leq N$	(39)
(STRIP (BAGA A 1 I-1)) \leq R \leq (STRIP (BAGA A J+1 NN))	(40)
$R \leq A[I]$	(41)
(BAGA AP 1 NN) = (BAGA A 1 NN)	(42)
$\neg (R < A[J])$	(43)
I ≤ J	(44)
$\neg (I+1 \le J-1)$	(45)
$F \leq J-1$.	(46)

The interesting consequence for this path is

(STRIP (BAGA A' 1 J-1))
$$\leq$$
 (STRIP (BAGA A' (J-1)+1 NN)) (47)

where

$$A' = (EXCHANGE A I J)$$

the array that results when elements A[I] and A[J] are interchanged in A.

The proof sketched below roughly parallels the proof produced by the inference system. Portions of the trace are shown in Appendix B.

The (J-1)+1 term in the goal (47), is simplified to J, giving the goal

```
(STRIP (BAGA A' 1 J-1)) \leq (STRIP (BAGA A' J NN)) (48)
```

The difficulty in the proof arises from the uncertainty about whether $J \leq I$. We are reasoning about an array segment, and it is not clear whether that segment is affected by the exchange or not. Hand analysis of hypothesis (44) and (45) reveals that I = J or I = J-1. The value of a term like (BAGA (EXCHANGE A I J) 1 J-1) depends on which possibility is actually the case.

The system "simplifies" the term into

```
(IF J \le I THEN (BAGA A 1 J-1)

ELSE (BAG (STRIP (BAGA A 1 I-1))

A[J]

(STRIP (BAGA A I+1 J-1)))
```

Intuitively, if $J \le I$, then both I and J are outside the bounds of the array segment, whereas if I < J, then the array segment loses A[I] but gains A[J].

Similarly, the term

(BAGA (EXCHANGE A I J) J NN)

is "simplified" into

```
(IF J \le I THEN (BAGA A J NN)

ELSE (BAG (STRIP (BAGA A J J-1))

A[I]

(STRIP (BAGA A J+1 NN)))
```

Note that (BAGA A J J-1) is empty; the ELSE clause is then

(BAG A[I] (STRIP (BAGA A J+1 NN)))

Our goal can thus be reduced to showing that

(IF
$$J \le I$$
 THEN (STRIP (BAGA A 1 J-1))
ELSE (STRIP (BAG (STRIP (BAGA A 1 I-1))
A[J]
(STRIP (BAGA A I+J J-1))))

≤

(IF
$$J \le I$$
 THEN (STRIP (BAGA A J NN))
ELSE (STRIP (BAGA A J +1 NN)))) . (49)

The system approaches the conditional expression by creating two contexts: In one context, $J \leq I$ holds, and in the other, I < J is true. In the first context we must prove that

(STRIP (BAGA A 1 J-1))
$$\leq$$
 (STRIP (BAGA A J NN)) . (50)

In the second context, the statement to be proved is

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Note that in the first context, J = I by (44). In working on (50), (BAGA A J NN) is expanded to (BAG A[J] (STRIP (BAGA A J+1 NN))). Thus, (50) breaks into two subgoals:

(STRIP (BAGA A 1 J-1))
$$\leq A\lceil J \rceil$$
 (52)

and

(STRIP (BAGA A 1 J-1))
$$\leq$$
 (STRIP (BAGA A J+1 NN)) . (53)

Since I = J, (52) follows from (40) and (41), and (53) follows from (40) alone.

Work on the goal (51) proceeds in the second context, in which $I \leq J$.

Since $J-1 \le I+1$ (11), we know (BAGA A I+1 J-1) is empty. The inequality (51) may thus be broken into four inequalities:

(STRIP (BAGA A 1 I-1))
$$\leq A[I]$$
 , (54)

(STRIP (BAGA A 1 I-1))
$$\leq$$
 (STRIP (BAGA A J+1 NN)) , (55)

$$A[J] \le A[I] , \qquad (56)$$

and

$$A\Gamma J$$
 \leq (STRIP (BAGA A J+1 NN)) . (57)

Line (54) follows from hypotheses (40) and (41). Goal (55) follows from (40). Goal (57) follows from (43) and (40). This completes the proof.

This proof is the longest achieved by our deductive system so far.

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X SUMMARY OF RESULTS

Complete proofs have been found of the correctness of the following algorithms:

- Finding the largest element of an array
- Finding the quotient of two real numbers
- Hoare's FIND program
- The Euclidean algorithm for finding the greatest common divisor
- The exponentiation program from King's thesis
- Integer quotient and remainder
- Integer multiplication by repeated addition
- The factorial.

Theorems have been proved about the following algorithms:

- The pattern matcher.
- Unification.
- Exchanging two array elements (the theorem is that the bag of the contents of the array is unchanged).
- King's exchange sort.

We believe the system now has the power to do all of King's problem set except the linear inequalities problem, which is not really a proof about an algorithm.

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XI FUTURE PLANS

We are currently applying the verifier to more and more complex programs in a variety of subject domains. We are continuously being forced to add new rules and occasionally to generalize old ones; a special purpose rule that worked for one problem may not work for the next.

The deductive system is implemented in the QA4 language. Although QA4 is ideally suited for expressing our rules, it is an experimental system evaluated by an interpreter and is written in LISP; furthermore, it uses space inefficiently. R. Reboh and E. Sacerdoti are in the process of integrating QA4 into BBN-LISP to produce a system known as QLISP [Reboh and Sacerdoti, 1973]. QLISP programs will be LISP programs that can be evaluated by the LISP interpreter or even compiled. Furthermore, QLISP is much more conservative in its use of space. We expect that this system will be considerably faster and more compact than the existing system. Our deductive system is already being translated into QLISP.

QA4 subtly encourages its users to write depth-first search strategies, since it implements the goal mechanism by means of backtracking. The deductive system uses depth-first search, and for the most part, this has been the proper thing to do. There have been times, however, when we have felt the need for something more discriminating. Suppose, for example, we are trying to prove an expression of the form x = y. We can do this by trying to simplify x and then proving that the simplified x is equal to y, or we can try to find some assertion a = b and prove x = a and y = b. In the current system, we must exhaust one possibility before trying another, whereas we would like to be able to switch back and forth between different approaches, giving more attention to the one

that currently seems to be making the best progress. In other words, we hope to use processes rather than backtracking in the implementation of the goal mechanism.

Finally, we hope to apply this work to the generation of counter-examples for "wrong" programs, to the generation of Floyd assertions, and to the automatic construction of programs. It seems inevitable that if we know how to reason about programs, that reasoning should be able to help us in the process of forming or changing a program. Rather than taking a handwritten and hand-debugged program to a verifier for approval, we hope to collaborate with a system that will play an active role in the creation of the algorithm.

Appendix A

LISTING OF THE DEDUCTIVE SYSTEM

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Appendix A

THE DEDUCTIVE SYSTEM

The deductive system has the overall structure shown in Figure 4.

The names on the chart are either function names or goal classes. Only important substructures are included.

An annotated listing of the programs used for reasoning is presented below. An index of functions and goal classes is included at the end of this appendix. The reader will note how little of the space is devoted to general strategies and how much is devoted to subject-specific knowledge. Some of the programs use QA4 features that are not described in this paper. The reader can rely on the English explication of the programs, or he can refer to the QA4 manual (Rulifson et al. [1973]).

To start a deduction, we say to the system

(GOAL \$PROVE(some statement))

PROVE is a goal class:

(TUPLE ANDSPLIT ORSPLIT OPSPLITMANY PROOFSWITCH)

PROOFSWITCH determines whether the goal is an equality, otherwise
 it is assumed to be an inequality.

^{*} Bullets are used to indicate the beginning of the description of a new function.

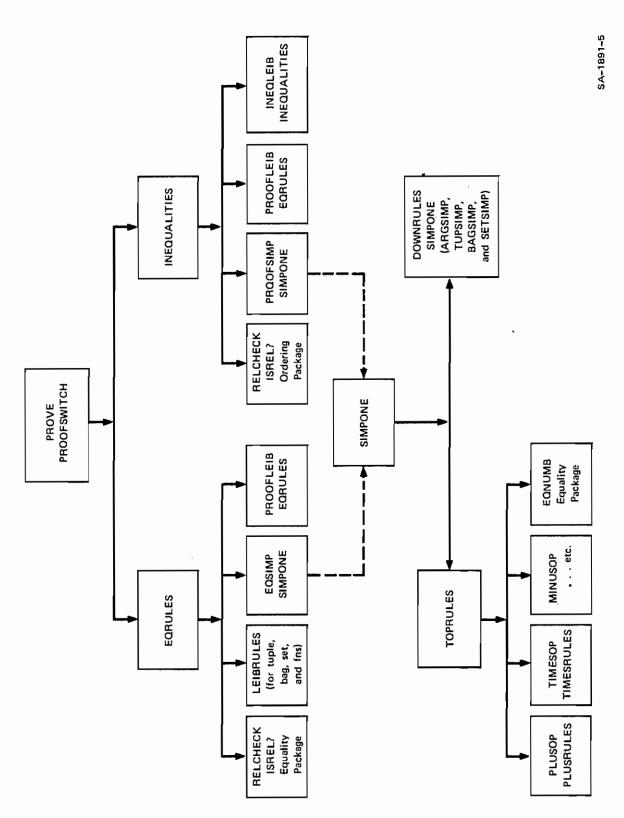


FIGURE 4 STRUCTURE OF THE DEDUCTIVE SYSTEM

```
PROOFSWITCH=(LANBDA (-F -X)
(PROG (DECLARE)
(IF (EQUAL $F (QUOTE EQ))
THEN
(GOAL #EQRULES ($F $X))
ELGE
(GOAL #INEQUALITIES
($F $X)))
(ASCERT ($F $X))
(RETURN ($F $X))
```

In either case, the appropriate set of rules is applied.

1. Equalities

The equality class is

```
EQRULES =
(TUPLE ANDOPLIT RELOHECK EQTIMESOTYIDE EQSUBST LETBT LETBF LETBB LETBS EQSIMP PROOFLET())
```

• The rule ANDSPLIT takes a goal that is a conjunction of two or more expressions and tries to prove each conjunct independently.

```
ANDSPLIT=(LAMBDA (AND +X ++Y)

(ATTEMPT (GOAL $GOALCLASS $X)

THEN

(ATTEMPT (GOAL $GOALCLASS

(AND $$Y))

ELSE

(FAIL))

ELSE

(FAIL)
```

If repeated applications of ANDSPLIT are successful eventually, the goal (AND) will be generated. However, (AND) is an assertion in the data base, and so the rule will then succeed.

• ORSPLIT applies to a goal that is the disjunction of two expressions

⁺ The right bracket represents a string of right parentheses long enough to balance the expression.

[‡] Variables with double prefixes, "→" or "\$\$," respectively match or evaluate to a sequence of terms rather than a single term. In the rule, for example, Y can be bound to a set of terms, including the empty set.

and works on each separately.

The expression x is attempted as a goal first; if this is successful, we are done. Otherwise, ORSPLIT works on y; if it is unsuccessful, then a failure is generated.

• ORSPLITMANY is similar to ORSPLIT, except that it takes as a goal the disjunction of three or more expressions:

The expression \mathbf{x} is attempted first; if the proof is successful, the disjunction is true. Otherwise, the disjunction of the remaining expressions is established as a new goal. Continued failure to prove members of a disjunction will eventually cause ORSPLIT to be invoked.

• The rule RELCHECK merely checks the property lists of the expressions to see if they are already known to be equal:

When RELCHECK is applied, x is bound to an equality statement, which is fed to the ISREL? statement. ISREL? will succeed not only if the equality has been explicitly asserted, but also if the equality follows by the transitive law from other equalities or inequalities. ISREL? is the mechanism for making queries about special relations. It will work with inequality relations, such as LT, GTQ, and NEQ, as well as EQ.

EQTIMESDIVIDE and EQSUBST are rules for reasoning about numbers and substitutions, respectively. They are discussed in the relevant sections.

```
LEIBF= (LAMBOA (EQ (AF AX))
                   (←F ←Y))
               (PROG (DECLARE)
                     ($ASK (* (EQ $X $Y))
                           PROVE?)
                     (GOAL $EORULES (EQ $X $Y)
LEIBT= (LAMBOA (EQ (TUPLE +X ++Z)
                    (TUPLE -Y -- LA))
               (PROG (DECLARE)
                      (GOAL $EQRULES (EQ $X $Y))
                      (GOAL $EQUULES (EQ $Z $W)
LEIBS=(LAMBDA (EQ (SET +X ++Z)
                   (SET +Y ++Z))
               (GDAL #EQRULES (EQ $X $Y)
LEIBB=(LAMBDA (EO (BAG +X ++Z)
                    (BAG +Y +--Z))
               (GOAL SEORULES (EQ SX SY)
```

The LEIBF rule asks the user if he wants that rule to be applied. The function ASK that performs the interaction is described in the section on utility functions.

• EQSIMP and PROOFLEIB are very time consuming but also very powerful. EQSIMP says that to prove x = y, simplify x and try to prove that the simplified x is equal to y.

```
EQSIMP=[LAMBDA (EQ +X +Y) (PROG (DECLARE) (SETQ +X ($SIMPONE $X)) (GOAL $EQRULES (EQ $X $Y))) BACKTRACK))
```

Since the program uses the BACKTRACK option, and since EQ implicitly takes a set as its argument, EQSIMP can work on y as well as on x. In other words, if it fails to simplify x, it will go ahead and try to simplify y.

PROOFLEIB tries to make use of information stored in the data base.
 It is used to prove inequalities as well as equalities.

PRODELETB = (LAMBDA (-F -X)
(PROG (DECLARE)
(EXISTS (%F -Y))
(MASK (* (EQ %X %Y))
PROVE?)
(GOAL %EQRULES (EQ %X %Y)

It says: to prove u = v, find an assertion of the form a = b and prove u = a and v = b. It relies on user interaction to cut off bad paths. Note that if F is EQ, we can expect X and Y to be sets, so that LEIBS will ultimately be called to prove the equality expression generated by PROOFLEIB.

2. Inequalities

We now turn to the rules for proving inequalities.

INEQUALITIES

(TUPLE AND SPLIT RELCHECK ORSPLIT ORSPLITMANY PROOFSIMP

INEQIFTHENELSE INEQSTRIPBAG INEQSTRIPSTRIP

INEQSTRIPTGAN GOOLTO LIQUANY FSUBTRACTI FSUBTRACT2

INEQTIMESDIVIDE EQINEQMONOTONE LIQUALUS PROOFLEIB

INEQLEIB))

RELCHECK has been mentioned above.

• GTQLTQ says that to prove $y \ge x$, try to prove $x \le y$:

LTQMANY takes an inequality goal, such as

$$x_1 \le x_2 \le \ldots \le x_n$$
,

and breaks it into separate goals,

$$x_1 \le x_2$$
 and $x_2 \le x_3$ and ... $x_{n-1} \le x_n$

LTQPLUS, FSUBTRACT1, and FSUBTRACT2 are special rules for reasoning about numbers and are discussed in the relevant section.

• PROOFSIMP proves an expression F(Y) by trying to simplify Y and proving the simplified expression.

```
PROOFSINE (LAMBDA (PAND -X (-F -Y))

(PROG (DECEASE GOALCLASSI)

(SETO -GOALCLASSI $COALCLASS)

(ATTEMPT (SETO -X ($ARGSIMP $X))

ELSE

(FAIL))

(GOAL $GOALCLASSI $X)
```

It has more general application than just to inequalities, although so far we have used it only for inequalities.

• INEQLEIB is similar to PROOFLEIB, but it works only for inequalities.

```
INEQUEIB=(LAMBDA (-L -X -Y)

(PROG (DECLARE LOWER UPPER))

(EXISTS (%L -LOWER -UPPER))

($ASK PROVE (' (LTQ %X $LOWER))

AND

(' (LTQ $UPPER $Y))

?)

(GOAL $INEQUALITIES

(AND (LTQ $UPPER $Y)
```

L is expected to be LT or LTQ. To prove x < y, for example, find an asserted statement LOWER < UPPER and prove $x \le$ LOWER and UPPER $\le y$.

INEQIFTHENELSE is a rule that sets up a case analysis:

```
INEQIFTHENELSE=(LAMBDA (+F ++W1 (IFTHENELSE +X +Y +Z)
                            ←←N2)
                        (PROG (DECLARE VERICON)
                              (ATTEMPT (SETQ AVERICON
                                             (CONTEXT PUSH
                                                      LOCAL))
                                       (ASSERT $X WRT $VERICON)
                                       THEN
                                       (GOAL $INEQUALITIES
                                             (8F $$W1 $Y $$W2)
                                             WRT SVERICON))
                              (ATTEMPT (SETQ -VERICON
                                             (CONTEXT PUSH
                                                       LOCAL))
                                       (DENY $X WRT $VERICON)
                                       THEN
                                       (GOAL $INEQUALITIES
                                             (SF 88W1 8Z 88W2)
                                             WRT SVERICON)
                                       ELSE
                                       (RETURN (SUCCESS WITH
                                             [NEQIFTHENELSE]
```

For example, suppose the goal is (IF x THEN y ELSE z) \leq w. This rule establishes two subcontexts of the local context. In one of these contexts, x is true; in the other, x is false. In the first context, the rule tries to prove y \leq w, whereas in the second, it tries to prove z \leq w. Note that the system that stores equalities and inequalities will cause a failure if an assertion (or a denial) would lead it to contradict what it knows. In that case the goal is considered to be achieved.

• INEQSTRIPBAG is an inequality rule that has a bag as one of its arguments.

```
INEGSTRIPBAG=(LAMBOA (+F ++W (STRIP (BAG +X ++Y))
++Z)
(GOAL $INEQUALITIES
(AND ($F $$W $X $$Z)
($F $$W (STRIP (BAG $$Y))
$$Z]
```

This rule would be invoked when we want to show, for example, $\mathbf{w}_1 \leq (STRIP \ (BAG \ \dot{\mathbf{c}}_1 \ \mathbf{c}_2 \dots)) \leq \mathbf{w}_2$. The intention here is to demonstrate that $\mathbf{w}_1 \leq \mathbf{c}_1 \leq \mathbf{w}_2$ and $\mathbf{w}_1 \leq \mathbf{c}_2 \leq \mathbf{w}_2$, and so forth. Ultimately, we might have to demonstrate that $\mathbf{w}_1 \leq (STRIP \ (BAG)) \leq \mathbf{w}_2$. The special relations handler (ISREL?) succeeds vacuously with any inequality relation where one of the arguments is (STRIP (BAG)).

3. Deduce

• DEDUCE is a goal class of rules that are guaranteed to terminate quickly. It is used when we want something more inquisitive than EXISTS but less timeconsuming than PROVE, EQRULES, or INEQUALITIES.

[/EDUCE=
(TUPLE RELCHECK ANDSPLIT ORSPLIT ORSPLITNANY LTPLUS FSUBTRACT1
 FSUBTRACT2 LTQPLUS NOTATOM CONSTCAR CONSTCDR))

We have already described RELCHECK.

The other DEDUCE rules are for special applications and are discussed in the appropriate sections.

4. Simplification

• The top-level simplification function is SIMPONE. This function does not try to simplify its argument completely. It will find a partial simplification; repeated applications, if necessary, will completely simplify the expression.

The simplification rules may, of course, be added by the user. We expect that each simplification rule should make the expression simpler in some sense. Otherwise, the program may loop interminably.

```
SIMPONE=(LAMBDA +GOALI (PROG (DECLARE SIMPGOAL)
                               (IF (EQUAL (STYPE #GOAL1)
                                          NUMBER)
                                   THEN
                                   (FAIL))
                               (BASK SGOAL1 SIMPLIFY?)
                               (SETQ -SIMPGOAL
                                     (ATTEMPT
                                        (GOAL STOPRULES SGOAL1)
                                        ELSE
                                        ($TRY $TOPRULES
                                              (GOAL $DOWNRULES
                                                    $GOAL11
                                (PUT $GOAL1 SIMPLIFIED $SIMPGOAL
                                     LIRT ETERNAL)
                                (RETURN $SIMPGOAL)
```

SIMPONE fails if it cannot simplify its argument at all. It treats numbers as being completely simplified. It asks the user for permission to go ahead. It tries a goal class, TOPRULES, on the expression.

TOPRULES is a set of rules that work on the top level of the expression:

COPPULES

(TUPLE HASSIMP FAILINTODOWNRULES PLUSOP TIMESOP MINUSOP

FILTHENELSE BAGAOP SUBSTOP EXPZERO EXPEXP SUBPLUS

SUBDIUM GCDFQ ACCH CONSDIFF DIFFCONS DIFFONE

HAXPLUS MAXONE BAGSTRIP ACCEX EQNUMB)

If any of these rules apply, SIMPONE returns the simplified expression as its value. Otherwise, it tries to simplify some subexpression of the given expression:

```
DOUGHQUES = (TUPLE ARGSIME TUPSIME BAGSIME SETSIME))

ARGSIME = (LAMBDA (-F -X)
(SUBST (' (SF SX))
(TUPLE $X ($SIMPONE $X)

HUPSIME = (LAMBDA (TUPLE --X -Y --Z)
(TUPLE $$X ($SIMPONE $Y)
$$Z)
BACKTRACKI)

BAGSIME = (LAMBDA (BAG -X --Y)
(BAG ($SIMPONE $X)
$$Y)
BACKTRACKI)

SETSIME = (LAMBDA (SET -X --Y)
(SET ($SIMPONE $X)
```

The DOWNRULES simplify a complex expression by simplifying the component parts of the expression. If any of the DOWNRULES apply, SIMPONE applies the TOPRULES again to the new expression. SIMPONE calls the functions ASK and TRY that are described in the section on utility functions.

\$\$Y) BACKTRACK])

• SIMPONE puts the simplified expression on the property list of the original expression. In this way, if it ever comes across the original expression again, one of the TOPRULES, HASSIMP, will immediately know what simplification was found before.

HASSIMP=(LAMBDA -X (IF (NOT (IN (SETQ -X (GET \$X SIMPLIFIED)))

(TUPLE DONE NOSUCHPROPERTY)))

THEN \$X ELSE (FAIL)

• If the expression to be simplified is a set, tuple or bag rather than a function application, none of the TOPRULES will apply to it. To avoid the cost of searching for a match among all the TOPRULES, the rule FAILINTODOWNRULES will first test for this condition and cause the entire goal statement to fail should it arise:

```
FAILINTODONNRULES⇒ (LAMBDA ←X

(IF (IN (STYPE $X)

(TUPLE TUPLE SET BAG))

THEN

(FAIL GOAL)

ELSE

(FAIL]
```

SIMPONE will then apply the DOWNRULES to the argument to see if any of its subexpressions can be simplified.

• One of the most general TOPRULES is EQNUMB, which replaces any expression by the "smallest" known equal expression:

```
EQNUMB = (LAMBDA -X (PROC (DECLARE BEST EQSET)
(IF (EQUAL (SETQ -EQSET (GET $X EQ))
NOSUCHPROPERTY)

THEN
(FAIL))
(SETQ -BEST ($SHORTEST $EQSET))
(IF (EQUAL $BEST $X)

THEN
(FAIL)
ELSE
(RETURN $BEST]
```

The "smallest" element of a set is computed by the QA4 function SHORTEST, described among the utility functions.

If EQNUMB fails to find a smaller representation for x, it fails.

```
FIFTHENELSE (LAMBDA (←F (IFTHENELSE ←W ←X ←Y))
(' ([FTHENELSE SW (SF SX)
(SF SY)
```

FIFTHENELSE moves conditional expressions outside of function applications.

An expression of the form

```
f(IF w THEN x ELSE y)
```

translates into

```
IF w THEN f(x) ELSE f(y)
```

The remaining rules in TOPRULES are discussed in the sections dealing with special subject domains.

5. Reasoning About Numbers

- a. Equality and Inequality Rules
- EQTIMESDIVIDE is an EQRULE. It means that to prove w = (x/y)*z, prove w*y = x*z:

```
EQTIMESUNVIDE=(LAMBDA (EQ +W (TIMES (DIVIDES +X +Y) ++-Z))

(GOAL SECHULES (EQ (TIMES SY SW) (TIMES SX SSZ)))

BACKTRACK))
```

Some inequality rules that know about numbers are presented below.

• LTQPLUS says that to prove $i \le j+k$, prove $i \le j$ and $0 \le k$:

First, the rule attempts to prove that $i \le j$ and $0 \le k$. If either of these proofs is unsuccessful, then the backtracking mechanism will interchange the bindings of the arguments of LTQPLUS. This then leads to an attempt to prove $i \le k$ and $0 \le j$.

• LTPLUS is the analogue of LTQPLUS for LT:

```
LTPLUS= (LAMRDA (LT +1 (PLUS +J +K))
(GOAL $DEDUCE (AND (LTQ $1 $J))
(LT 0 $K)))

BACKTRACK))
```

It means that to prove i < j+k, prove $i \le j$ and 0 < k. It can backtrack to reverse the roles of j and k.

FSUBTRACT1 and FSUBTRACT2 allow us to make deductions: for example, to prove $x-y \le z$ try to prove $x \le y+z$.

```
FOURTRACTI = (LAMBDA (*F (SUBTRACT *X *Y) *Z) (GOAL $GOALCLASS ($F $X (PLUS $Y $Z]) FOURTRACT2 = (LAMBDA (*F *X (GUGTRACT *Y *Z)) (GOAL $GOALCLASS ($F (PLUS $X $Z) $Y]
```

• INEQMONOTONE says that to prove w+x \leq y+z, prove w \leq y and x \leq z or w \leq z and x \leq y.

• The rule INEQTIMESDIVIDE is similar to EQTIMESDIVIDE except that it must check that the denominator is nonnegative before multiplying out:

```
INEQTIMESDIVIDE=[LAMBDA (\leftarrowF \leftarrowW (TIMES (DIVIDES \leftarrowX \leftarrowY) \leftarrowC))

[PROG (DECLARE)

(GOAL $DEDUCE (LT 0 $Y))

(GOAL $INEQUALITIES

($F (TIMES $Y $W)

(TIMES $X $$Z]
```

This rule says that to prove w < (x/y)*z, say, in the case that 0 < y, try to prove w*y < x*z.

- b. Numerical Demons
- When x ≥ y is asserted, assert that y < x:

(WHEN EXP (GTQ -X -Y) INDICATOR MODEEVALUE THEN (ASSERT (LTQ \$Y \$X) WRT \$VERICONI

These demons make their assertions with respect to the current context, VERICON.

• Whenever $x+y \le x+z$ is asserted, we want to conclude that $y \le z$:

(WHEN EXF (LTQ (PLUS -X -Y) (FLUS +X -Z)) INDICATOR MODELVALUE THEN (ASSERT (LTQ \$Y \$Z) WRT \$VERICON]

• Whenever w-x \leq y is asserted, assert w \leq x+y, simplifying the right side if possible:

(WHEN EXP (LTO (SUBTRACT +W +X) +Y)

INDICATOR MODELVALUE THEN
(PROG (DECLARE RTSIDE)
(SETQ +RTSIDE
(\$TRYALL \$PLUSRULES
(' (PLUS \$Y \$X]
(ASSERT (LTQ \$W \$RTSIDE)
WRT \$VERICON]

• Whenever $(w-x)+x \le y$ is asserted, then assert $w \le y$:

(WHEN EXP (LTQ (PLUS (SUBTRACT +W +X) +X) +Y) INDICATOR MODELVALUE THEN (ASSERT (LTQ \$W \$Y) WRT \$VERICON]

Certain demons are intended exclusively for the integer domain.

• $x < y \supset x+1 \le y$:

(WHEN EXP (LT ←X ←Y)
INDICATOR MODELVALUE THEN
(ASSERT (LTQ (PLUS \$X 1)
\$Y)
WRT \$VERICON]

• $x > y \supset y+1 \le x$:

(WHEN EXP (GT ←X ←Y)
INDICATOR MODELVALUE THEN
(ASSERT (LTQ (PLUS \$Y 1)
\$X)
URT \$VERICON)

Whenever w-x < y is denied, deny $w \le y+x-1$, simplifying if possible:

(WHEN EXP (LT (SUBTRACT +W +X)

LY)

INDICATOR MODELVALUE PUTS FALSE THEN
(PRDG (DECLARE RTSIDE)

(SETQ

+RTSICE

(\$TRYALL \$PLUSRULES

(" (PLUS \$Y \$X

(MINUS 1)

(DENY (LTQ \$W \$RTSIDE)

WRT \$VERICON)

c. Numerical Simplification

Much of the knowledge the system has about numbers is embedded in the simplifier. For efficiency, these rules have been arranged hierarchically. For example, only one rule, PLUSOP, in TOPRULES deals with sums.

However, this one rule coordinates a multitude of other rules. All the rules that operate on plus expressions are in the goal class PLUSRULES.

```
PLUSRULES= (TUPLE PLUSEMPTY PLUSSINGLE PLUSZERO PLUSPLUS PLUSMINUS PLUSDIFFERENCE PLUSCOMBINE PLUSNUMBER))
```

The strategy PLUSOP uses is to apply all the PLUSRULES to its argument until no further simplification is possible. (The function TRYALLFAIL, that expresses this strategy, is described among the utility functions.) If PLUSOP can find no simplification at all, it fails.

Most of the PLUSRULES are quite simple.

The sum of the empty bag is 0:

The sum of a bag of one element is that element itself:

(i.e., +x = x).

 $\bullet \qquad x+0 = +x \quad :$

PLUSZERO=(LAMBDA (PLUS ++X 0) (* (PLUS \$\$X)

Note that this rule implicitly says

$$0+x = +x$$

 $x+0+y = x+y$
 $x+y+0+z = x+y+z$

and so forth because PLUS takes a bag as its argument.

•
$$((x_1+x_2+...)+y_1+y_2+...) = (x_1+x_2+...+y_1+y_2+...)$$
:

• x+(-x)+y = +y:

• x+(y-z)+w = x+y+w+(-z) :

```
PLUSDIFFERENCE =(LAMBDA (PLUS -X (SUBTRACT -Y -Z) +-W)

($TRY (TUPLE PLUSMINUS)

(" (PLUS $Y $X $$W (MINUS $Z]
```

Note that PLUSDIFFERENCE recommends that PLUSMINUS be attempted immediately afterward. This is merely advice; if PLUSMINUS does not apply, nothing is lost. (TRY is described in the section on utility functions.)

 $\bullet \qquad x+x+y = 2*x+y$

Note that PLUSCOMBINE recommends that the 2*x term be simplified if possible.

• If two elements of a plus expression are syntactically numbers, PLUSNUMBER will add them up:

```
$$Y]

PLUSNUMBER=[LAMBDA (PLUS \( \text{CY \( \text{CY \( \text{CV \( \text{CV \\ (\text{EQUAL \( \text{STYPE \( \text{SX} \) \)} \)}} \)

\( (\text{SINSIST \( \text{EQUAL \( \text{STYPE \( \text{SY} \)} \)} \)

\( (\text{SINSIST \( \text{EQUAL \( \text{STYPE \( \text{SY} \)} \)} \)

\( (\text{SETQ \( \text{CSUM \( \text{CSUM \( \text{SSUM \( \text{SUM \( \text{SSUM \( \text{SSUM \( \text{SSUM \( \text{SSUM \( \text{SUM \( \text{SSUM \( \text{SUM \( \text{SSUM \( \text{SUM \) \) \\  \) \\  \) \\  \) \\  \)
```

• The rule TIMESOP is strategically similar to PLUSOP:

```
TIMESOP =(LAMBDA (PAND -Y (TIMES -+X))
(STRYALLFAIL STIMESRULES SY))
```

It will apply all the TIMESRULES to the expression in question. TIMESRULES is

TIMESRULES = (TUPLE TIMESEMPTY TIMESSINGLE TIMESZERO TIMESONE TIMESPLUS TIMESTIMES CANCEL SQRULE TIMESEXP TIMESDIVIDEONE))

The product of the empty bag is 1:

TIMESEMPTY = (LAMBDA (TIMES)

The product of a bag of one element is that element itself:

TIMESSINGLE = (LAMBDA (TIMES +X)
8X))

• 0*y = 0:

TIMESZERO=(LAMBDA (TIMES 0 +-Y) 01)

• 1*x = x:

TIMESUNE=(LAMBDA (TIMES 1 ++X)
(' (TIMES \$\$X)

Recall that these rules also imply

$$x*1*y = x*y$$
,
 $x*0*y*z = 0$,

and so forth.

• (x+y)*z = x*z+(+y)*z (distribution law):

TIMESPLUS=(LAMBDA
(TIMES (PLUS +X ++Y)
++Z)
(\$TRY \$PLUSRULES (\$TRYSUB \$PLUSRULES ON (' (PLUS \$\$Y))
IN
(' (PLUS (TIMES \$X \$\$Z)
(TIMES (PLUS \$\$Y))
\$\$Z]

(Some simplification is attempted immediately on y and on x*z + y*z.

TRYSUB is explained in the section on utility functions.)

(MINUS \$X)

(GDAL (TUPLE MINUSZERO MINUSMINUS MINUSPLUS)

Note the MINUSOP, unlike PLUSOP and TIMESOP, does not apply \underline{all} the rules to the expression, but will return the value of the first rule that does not fail.

• -0 = 0 :

 $\bullet \quad \neg(\neg x) = x :$

 \bullet -(x+y) = (-x)+(-y)

At present there are only two subtraction rules, and so we do not combine them into one operator:

 $\bullet \qquad x-y = x+(-y) \quad :$

ullet If x and y are both numbers and not variables, SUBNUM actually evaluates x-y:

```
SUBNUM=(LAMBDA (SUBTRACT +X +Y)
(PROG (DECLARE)
($INSIST (AND (EQUAL (STYPE $X NUMBER)))
(EQUAL (STYPE $Y)
NUMBER)))
(RETURN (= (SUBTRACT $X $Y)
```

The "=" sign forces the system to evaluate what it would otherwise merely instantiate. INSIST is another utility function.

Two more rules about exponentiation are given below.

•
$$\mathbf{x}^0 = \mathbf{1}$$
 : EXPZERO = (LAMBDA (EXP $+$ X 0) 11)

• $(\mathbf{x}^y)^z = \mathbf{x}^{y*z}$:

EXPEXP= (LAMBDA (EXP (EXP $+$ X $+$ Y) +Z) (STRYSUB STIMESRULES ON (' (TIMES SY SZ)) IN (' (EXP $+$ X (TIMES SY $+$ Z))

Note that EXPEXP recommends that the TIMESRULES be applied to the product y*z; this is heuristic advice that could have been omitted.

• (GCD x x) = x

I-CDEQ =LAMBDA (GCD ←X ←Y)

(PROG (DECLARE)

(GOAL \$DEDUCE (EQ ←X ←Y))

(RETURN \$X]

The GCD is the greatest common divisor.

(ACCESS (CHANGE A I T) I) = T

6. Reasoning About Arrays

Most of the knowledge about arrays embedded in the system is expressed as simplification rules.

(MAXA A I J+1) = A[J+1]

On the other hand, if

(MAXA A I J) > A[J+1]

then

(MAXA A I J+1) = (MAXA A I J)

MAXPLUS =(LAMBDA

(MAXA AA AL (PLUS AJ 1))

(PEOG (DECLARE)

(ACCESS \$A (PLUS \$J 1)

THEN

(RETURN (ACCESS \$A (PLUS \$J 1))

(GOAL \$DEDUCE (LT (ACCESS \$A (PLUS \$J 1)))

(MAXA \$A \$1 \$J)))

(RETURN (MAXA \$A \$1 \$J))

• Recall that (BAGA A I J) is the bag $[A[i], A[i+1], \ldots A[j]]$. Because of the crucial part this function plays in assertions about sortlike programs, we have many rules for it.

BAGARULES =

(TUPLE DAGAPLUS BAGAEMPTY BAGAII ARGSIMP BACH BAGEX BAGEX1

BAGAMINUS BAGALOWERPLUS BAGEXCOMPLICATED))

These rules are controlled by the rule BAGAOP, one of the TOPRULES:

BAGAOP=[LAMBDA (PAND +Y (BAGA ++X))
(STRYALLFAIL SBAGARULES SY])

Thus, the BAGARULES will be tried whenever we are simplifying an expression of the form (BAGA A I J).

• If $I \leq J+1$, then (BAGA A I J+1) = (BAG A[J+1] (STRIP(BAGA A I J))):

RAGAPLUS=(LAMBDA (BAGA +A +1 (PLUS 1 +J))
(PROG (DECLARE)
(GOAL \$DEDUCE (LTQ \$1 (PLUS 1 \$J)))
(RETURN (BAG (ACCESS \$A (PLUS \$J 1))
(STRIP (BAGA \$A \$1 \$J)

ACCH is one of the TOPRULES, as are the rules below, ACCEX, MAXONE, MAX, and MAXPLUS.

• (EXCHANGE A I J) is a higher level function whose output is the array A with the values of A[I] and A[J] exchanged. The value of (ACCESS (EXCHANGE A I J) K) depends on whether or not K equals I or J, i.e., whether the element here accessed was affected by the exchange. If K = I, the value is A[J]. If K = J, the value is A[I]. If K is neither I nor J, the value is the original value of A[K], since that location has not been affected by the exchange. The rule fails if it cannot be determined that K= I or K=J. This information is embodied in the rule ACCEX:

```
ACCEX=(LAMBDA (ACCESS (EXCHANGE +A -I +J)
-K)
(PROG (DECLARE)
(ATTEMPT (GOAL $DEDUCE (EQ $K $1))
THEN
(RETURN (ACCESS $A $J)))
(ATTEMPT (GOAL $DEDUCE (EQ $K $J))
THEN
(RETURN (ACCESS $A $1)))
(GOAL $DEDUCE (AND (NEQ $K $1)
(NEQ $K $J)))
(RETURN (ACCESS $A $K)
```

The maximum of an array, MAXA, is a function of three arguments:
 the array, the lower bound, and the upper bound.

$$(MAXA A I J) = (MAX A[I], A[I+1], ..., A[J])$$

$$(MAXA A I I) = A[I]:$$

• If (MAXA A I J) $\leq A[J+1]$, then

• If I < J, (BAGA A J I) is the empty bag:

```
BAGAENPTY≅(LAMBDA (BAGA FA F.L.F.)
(PROG (DELLAGE)
(GOAL $DEDUCE (LT $1 $J))
(RETURN (BAG)
```

(BAGA A I I) is [A[I]]:

```
BAGATI=(LAMBDA (BAGA 4A 61 43)
(PROG (DECLARE)
(GOAL $DEDUCE (EQ $1 $3))
(RETURN (BAG (ACCESS $A $1)
```

• If $I \leq J$, then (BAGA A I J) = (BAG (STRIP (BAGA A I J-1)) A[J]:

```
BACAMINUS=(LAMBDA
(BAGA FA FI FJ)
(PROG (DECLARE)
($INSIST (EQUAL (STYPE $J)
IDENT))
(GDAL $DEDUCE (LTQ $I $J))
(RETURN (BAG (ACCESS $A $J)
(STRIP (BAGA $A $I (SUBTRACT $J 1)
```

Since this rule would apply so often, it is restricted by forcing J to be an identifier rather than a complex expression.

If L ≤ M, then

```
(BAGA A L M) = (BAG A L M) = (STRIP (BAGA A L M)):
```

```
BAGALOWERPLUS=

(LAMBDA (BAGA GARNAME AL AM)

(PRUG (DECLARE F LOWER UPPER W)

(EXISTS (AF GAV (STRIP (BAGA GARNAME ALDWER AUPPER))

GOAL SDEDUCE (EQ SLOWER (PLUS 1 $L)))

(RETURN (BAG (ACCESS GARNAME $L)

(STRIP (BAGA GARNAME (PLUS 1 $L))
```

This rule tries to determine if its application is desirable by checking in the model for any relationship involving an array segment with

lower bound equal to L+1; if no such relationship exists, it is doubtful that the proposed simplification will lead to a proof.

• If $I \le J \le K$, then

```
(BAGA (CHANGE A J T) I K) =

(BAG T (STRIP (BAGA A I K))) ~ (BAG A[J])
```

On the other hand, if J < I or K < J,

```
(BAGA (CHANGE A J T) I K) = (BAGA A I K)
```

(The notation ~ means the difference between two bags.) In other words, making an assignment to an array element whose index is outside the bounds of a segment does not affect the segment. However, if the index is within bounds of the segment, then the corresponding bag will lose the old value of the array element but gains the new value:

```
BAUH =
(LAME:DA
  (BAGA (CHANGE +A +J +T)
        -I -K)
  (PBOG
    (DECLARE)
    [ATTEMPT
       (GOAL SDEDUCE (LTQ $1 $J $K))
       NBHT
       (RETURN
         (=
           ($TEY
             $DIFFRULES
             (STRYSUB
               (TUPLE ACCH ACCEX)
               UN
               (' (ACCESS SA SJ))
               ΙN
               ($TRYSUB $BAGARULES ON (' (BAGA $A $1 $K))
                            (DIFFERENCE (BAG ST
                                              (STRIF (BAGA SA SI SK)))
                                         (BAG (ACCESS SA SJ)
     (GOAL $DEDUCE (OR (LT $J $1)
                        (LT $K $J)})
     (RETURN (BAGA SA SI SK)
```

The rule BACH contains many recommendations about possible future simplifications. These recommendations are included to promote efficiency; the simplifier would eventually try the recommended rules even if the advice were omitted. The advice-giving functions TRY and TRYSUB are described in the section on utility functions.

• As mentioned above, (EXCHANGE A I J) is the array A with the values of A[I] and A[J] interchanged. If I and J are either both inside or both outside an array segment, then the exchange operation has no affect on the bag corresponding to that segment:

```
BAGEX (LAMBDA (BAGA (EXCHANGE 4A 41 4J)
                      -L -M)
                (PROG (DECLARE)
                      (GOAL SDEDUCE (LTQ $1 $J))
                      (ATTEMPT
                        IGOAL SDEDUCE
                               (OR (AND (LTQ $L $1))
                                        (LTQ $J $M))
                                   (LT SJ SL)
                                   (LT $M $1)
                                   (AND (LT $1 $L)
                                        (LT 8M $J)
                        THEN
                        (RETURN (BAGA SA SL SM))
                        ELSE
                        (FAIL)
```

For simplicity, BAGEX requires that I \leq J.

• If elements A[I] and A[J] are exchanged, and if J is in the array segment and I is not, or if I is in the segment and J is not, then the corresponding bag is indeed affected by the exchange operation. For instance, in the case in which J is in the segment and I is not, if the segment is bounded by L and M, the new bag is

```
(BAG (STRIP (BAGA A L J-1)
A[I]
(STRIP (BAGA A J+1 M))) :
```

```
BAGEXI =
(LAMBDA)
  (BAGA (EXCHANGE ←A ←I ←J)
        -L --M}
  (PROG (DECLARE)
         (GDAL SDEDUCE (LTQ $1 $J))
         (ATTEMPT (GOAL $DEDUCE (AND (LT $1 $L)
                                       (LTQ SL SJ)
                                       (LTQ $J $M)))
                  THEN
                   (RETURN (BAG (STRIP (BAGA $A $L (SUBTRACT
                                                $J 1)))
                                 (ACCESS SA SI)
                                 (STRIP (BAGA $A (PLUS 1 $J)
         (ATTEMPT (GOAL SDEDUCE (AND (LT $M $J)
                                       (LTQ $L $1)
(LTQ $1 $M)))
                  THEN
                   [RETURN (BAG (STRIP (BAGA $A $L (SUBTRACT
                                                 $[ 1)))
                                 (ACCESS $A $J)
                                 (STR)F (BAGA $A (PLUS 1 $1)
                                              [112
                  ELSE
                   (FAIL)
```

• BAGEXCOMPLICATED handles the case in which it can be determined that one of the exchanged elements is within or outside the array segment, but the location of the other array element is uncertain. The result is then a conditional expression. For example, if J is known to be outside the segment but I is only known to be greater than or equal to the lower limit L, the result is

```
(IF M < I THEN (BAGA A L M)

ELSE (BAG (STRIP (BAGA A L I-1))

A[J]

(STRIP (BAGA A I+1 M))))
```

```
EMAGENCOMPLICATED =
(LAMBDA
  (BAGA (EXCHANGE -A -I -J)
        -L -11)
  (PRUG (DECLARE)
         (BOAL $DEDUCE (LTQ $1 SJ))
         LATTEMPT (UCAL $DEDUCE (AND (LTO $L $1)
                                      (LT() $M $(11))
                  THEN
                  (RETURN (IFTHENELSE
                             (LT $M $1)
                             (BAGA SA SL SM)
                             (BAG (STRIF (BAGA $A $L (SUBTRACT $! 1)))
                                  (ACCESS $A $J)
                                  (STRIP (BAGA SA (FLUS 1 $I)
                                               $11
        (ATTEMPT (GOAL $0EDUCE (AND (LTQ $J $M)
                                      (LTQ $L $J)))
                  THEN
                  TRETURN (IFTHENELSE
                             (LTQ $L $I)
                             (BAGA SA SL SM)
                             (BAG (STRIP (BAGA SA SL (SUBTRACT SJ 1)))
                                  (ACCESS SA $1)
                                  (STRIP (BAGA $A (FLUS 1 $J)
                                               [[118
                  ELSE
                  (FAIL)
```

BAGEXCOMPLICATED comes after BAGEX and BAGEX1 in the goal class BAGARULES because we prefer the definite answer they provide to the conditional expression returned by BAGEXCOMPLICATED.

All the rules in this section have been simplification rules. There also are two inequalities rules that pertain to arrays, INEQSTRIPTRAN and INEQSTRIPSTRIP.

• To prove that every element in an array segment is less than (or less than or equal to) some quantity C, find an array segment that properly contains the given segment such that every element in the larger segment is less than some element D that is, in turn, less than or equal to C:

```
INEOSTRIPTRAN =
(LAMRDA (+F (STRIP (BAGA ←ARNAME ←L ←M))
      ←C)
      (PROG (DECLARE LOWER UPPER D)
            (EXISTS ($F (STRIP (BAGA $ARNAME ←LOWER ←UPPER))
            ←D))
      (GOAL $DEOUCE (AND (LTQ $LOWER $L')
            (LTQ $M $UPPER)
            (LTQ $D $C]
```

• To prove some ordering relation < or \le , between all the elements of two array segments, S_1 and S_2 , find relations of the same sense involving S_1' and C, and involving D and S_2' . Then show that S_1' and S_2' contain S_1 and S_2 respectively, and that C is less than or equal to D.

```
INEQSTRIPSTRIP=
(LAMBDA (+F (STRIP (BAGA +A +I +J))
            (STRIP (BAGA +A +K +L)))
        (PROG (DECLARE LOWER1 UPPER1 LOWER2 UPPER2 C D)
               (ATTEMPT (EXISTS (SF (STRIP (BAGA SA +LOWER1
                                                  ←UPPER1))
                                    +C))
                        [EXISTS ($F ←D
                                    (STRIP (BAGA $A ←LOWER2
                                                  ←UPPER21
                        (GOAL $DEDUCE (AND (LTQ $LOWER1 $1)
                                            (LTQ $J $UPPER1)
                                            (LTQ $LDWER2 $K)
                                            (LTQ $L $UPPER2)
                                            (LTQ $C $D)))
                        ELSE
                        (FAIL)
```

7. Reasoning About Bags

We have accumulated a number of rules about bags. Many of these rules have set-theoretic counterparts, which could have been included, but we have needed only bags in our proofs.

We use the QA4 function DIFFERENCE to mean the difference between bags, written informally as " \sim " .

 $cons(x, y \sim z) = cons(x, y) \sim z$:

CONSDIFF (LAMBDA =(CONS *X (DIFFERENCE +Y **+Z)) (* (DIFFERENCE +CONS *X *Y) **Z)

 $(x \sim y) \sim z = x \sim y \sim z$:

OIFDIF=(LAMBDA (DIFFERENCE (DIFFERENCE +X ++Y) -+Z) (' (DIFFERENCE \$X \$\$Y \$\$Z]

 $cons(x,y) \sim (BAG x) \sim u = x \sim u$:

(DIFFERENCE x) is taken to be x itself:

OTFFONE=[LAMBDA (DIFFERENCE ←X) \$X])

(BAG (strip x)) = x:

BAGSTRIP=[LAMBDA (BAG (STRIP +X))
\$X])

8. Reasoning About Substitutions

The rules in this section were added to prove assertions about the pattern matcher and the unification algorithm.

An atom is either a variable or a constant;

 $\neg var(x) \land \neg const(x) \supset \neg Atom(x)$:

```
NOTATON⊨ (LAMBDA (NOT (ATOM ~X))
(PROG (DECLARE)
(EXISTS (NOT (VAR $X)))
(EXISTS (NOT (CONST $X)
```

• If an expression is made of constants, so is the car and the cdr of the expression:

CONSTCAR=(LAMBDA (CONSTEXP (CAR +X)) (EXISTS (CONSTEXP \$X))

CONSTCOR=(LAMBDA (CONSTEXP (CDR +X))

(EXISTS (CONSTEXP \$X)

NOTATOM, CONSTCAR, and CONSTCDR are DEDUCE rules.

• The empty substitution does not change the expression:

No substitution changes an expression made up entirely of constants:

SUBSTEMPTY and SUBSTCONST are simplification rules.

To prove

$$varsubst(s, car(x)) = car(y)$$

prove

$$varsubst(s,x) = y$$

Similarly, to prove

$$varsubst(s, cdr(x)) = cdr(y)$$

prove

$$varsubst(s,x) = y$$

```
SUBSTOOR=(LAMBDA (EQ (MARSUBST 4S1 (CDR 4X))
                      (CDR ←Y))
                  TODAL SEQUELES (EQ (VARSUBST $S1 $X)
                                     5Y]
```

```
To prove
                            varsubst(s, x) = y
where x and y are nonatomic, prove
                      varsubst(s, car(x)) = car(y)
and
                      varsubst(s, cdr(x)) = cdr(y)
          SUBSTOONS=(LAMBDA (EQ (VARSUBST +S1 +X)
                             (PROG (DECLARE)
                                   (GOAL *DEDUCE (NOT (ATDM $X)))
                                   (GDAL $DEDUCE (NDT (ATOM $Y)))
                                   (GOAL (= (BREMOVE EQSUBST FROM
                                                    SECRULES))
                                        (EQ (VARSUBST $S1 (CAR $X))
```

SUBSTCAR, SUBSTCDR and SUBSTCONS are equality rules. They are clustered together in a goal class:

EQSUBSTRULES=(TUPLE SUBSTCAR SUBSTCARCOR SUBSTCARCOR))

(CAR \$Y))) (GOAL (= (\$REMOVE EQSUBST FROM

(DDR BY)

#EGRULES))

(EQ (VARSUBST \$S1 (CDR \$X))

EQSUBSTRULES is called from EQSUBST, an EQRULE.

```
FOSUBST= (LAMBDA (PAND FY (EQ (VARSUBST FS FX)
                               ←Z))
                 (GOAL $EQSUBSTRULES $Y1)
```

Note that SUBSTCONS removes EQSUBST from the EQRULES. This prevents the system from looping by applying SUBSTCONS followed by SUBSTCAR.

To prove

```
varsubst(s,u) = varsubst(s,v)
where u and v are nonatomic, prove
               varsubst(s, car(u)) = varsubst (s, car(v))
```

```
and
```

```
varsubst(s, cdr(u)) = varsubst(s, cdr(v))
           SUBSTCARCOR=(LAMBDA (EQ (VARSUBST -S -U)
                                    (VARSUBST -S -V))
                                (PROG (DECLARE)
                                      (GOAL SDEDUCE (NOT (ATOM $U)))
                                      (GOAL $DEDUCE (NOT (ATOM $V)))
                                      IGOAL SEQUULES
                                            (EQ (VARSUBST $S (CAR $U))
                                                (VARSUBST $S (CAR $V)
                                      (GOAL SEQRULES
                                            (EQ (VARSUBST $S (CDR $U))
                                                (VARSUBST $S (CDR $V)
     Substitutions are represented as lists of dotted pairs.
  If v is a variable,
                         varsubst(((v \cdot y)), v) = y
                SUBSTLIST=[LAMBOA (VARSUBST (LIST (CONS +V +Y))]
                                             ∠V)
                                   (PROG (OECLARE)
                                         (EXISTS (VAR $V))
                                         $Y))
     The composition operator has the property:
      varsubst(compose(s1, s2), x) = varsubst(s1, varsubst(s2, x))
        SUBSTCOMPOSE = (LAMBDA (VARSUBST (COMPOSE +S1 +S2)
                                        ←X }
                              (STRY SSUBSTRULES
                                    (' (VARSUBST $S1 (VARSUBST $S2 $X]
     These simplification rules are members of the goal class
        SUBSTRUCES=(TUPLE SUBSTENETY SUBSTLIST SUBSTCOMPOSE SUBSTCONST)
which is called by SUBSTOP, a member of TOPRULES:
                    SUBSTOP=(LAMBDA (PANO (VARSUBST ++X)
                                          -Y}
                                     (GDAL $SUBSTRULES $Y1)
```

9. Utility Functions

• TRY is like a GOAL statement that will not fail if none of the goal class apply but instead returns its argument.

(RY=(LANBDA (TUPLE =GOALCLASS =GOAL1) (ATTEMPT (GOAL \$GOALCLASS \$GOAL1) ELSE \$GOAL1)

It evaluates (GOAL \$GOALCLASS \$GOAL1), but, if failure results, it returns GOAL1.

• TRYALL will try a goal class on an expression. If any member of the goal class applies, it will apply the same goal class to the resulting expression, and so on, until no rules applies. TRYALL returns the last expression it has derived, which may be the same as the first expression. TRYALL will not fail:

TRYALL = (LAMBDA (TUPLE -GOALCLASS1 -GOAL1)

(PROG (DECLARE)

TOP

(ATTEMPT (SETQ -GOAL1 (GOAL \$GOALCLASS1 \$GOALCLASS1))

THEN

(GO TOP))

(RETURN \$GOAL1]

• TRYALLFAIL is like TRYALL, except it will fail if none of the goal class apply to the argument.

TRYALLFAIL=(LAMBDA (TUPLE -GOALCLASS1 -GOAL1)
(\$TRYALL \$GOALCLASS1 (GOAL \$GOALCLASS1 \$GOALCLASS1)

• TRYSUB applies a goal class to a specially designated subexpression of the given expression:

TRYSUB =(LAMBDA (TUPLE -GOALCLASS ON -SUB IN -EXP)
(SUBST SEXP (TUPLE SSUB (STRYALL SGOALCLASS SSUB)

INSIST fails if its argument is FALSE.

INSISTE(LAMBDA -X (IF \$X ELSE (FAIL)

REMOVE removes a designated item from a tuple.

```
REMOVE= [LAMBOA (TUPLE ←X FROM ←Y)
((QUOTE (LAMBOA (TUPLE ←←U $X ←←V)
(TUPLE $$U $$V])
$Y])
```

ASK queries the user:

```
ASK=(LAMBDA ←X (IF (LISP ASK $X)
ELSE
(FAIL]
```

It types two expressions, the first a QA4 expression (\$Y) and the second an atom(\$X; e.g., PROVE? or SIMPLIFY?). If the user types YES, TRUE, OK, Y, or T, say, ASK returns TRUE. Otherwise ASK fails. ASK uses a LISP function of the same name.

• SHORTEST computes the "smallest" element of a set, bag, or tuple:

The size of an expression is roughly the number of atoms in the expression. It is computed by a LISP function, QA4COUNT. Numbers are assumed to be "smaller" than identifiers.

Table A-1 gives an index of functions and goal classes.

Table A-1

INDEX OF FUNCTIONS AND GOAL CLASSES

NAME	PAGE	NAME	PAGE
ACCEX	80	EQSUBST	89
ACCH	78	EQSUBSTRULES	89
ANDSPLIT	59	EQTIMESDIVIDE	69
ARGSIMP	67 ·	EXPEXP	78
ASK	92	EXPZERO	78
BACH	82	FAILINTODOWNRULES	68
BAGAEMPTY	81	FIFTHENELSE	68
BAGAII	81	FSUBTRACT1	70
BAGALOWERPLUS	81	FSUBTRACT2	70
BAGAMINUS	81	GCDEQ	78
BAGAOP	79	GTQLTQ	62
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BAGARULES	79	INEQIFTHENELSE	64
BAGEX	83	INEQLEIB	63
BAGEX1	84	INEQSTRIPBAG	64
BAGEXCOMPLICATED	85	INEQSTRIPSTRIP	86
BAGSIMP	67	INEQSTRIPTRAN	86
BAGSTRIP	87	INEQTIMESDIVIDE	70
CANCEL	76	INEQUALITIES*	62
CONSDIFF	87	INSIST	91
CONSTCAR	88	LEIBB	61
CONSTCDR	88	LEIBF	61
DEDUCE*	65	LEIBS	61
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DIFFONE	87	LTQMANY	62
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DOWNRULES*	67	MAXONE	80
EQINE QMONOTONE	70	MAXPLUS	79
EQNUMB	68	MINUSMINUS	77
EQRULES*	59	MINUSOP	· 7 6
EQSIMP	61	MINUSPLUS	77

^{*}Goal class.

Table A-1 (Concluded)

INDEX OF FUNCTIONS AND GOAL CLASSES

NAME	PAGE	NAME	PAGE
MINUSZERO	77	SUBSTRULES	90
NOTATOM	88	TIMESDIVIDEONE	76
ORSPLIT	60	TIMESEMPTY	75
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PLUSNUMBER	74	TIMESSINGLE	75
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SIMPONE	66		
SQRULE	76		
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SUBPLUS	77		
SUBSTCAR	88		
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SUBSTCDR	89		
SUBSTCOMPOSE	90		
SUBSTCONS	89		
SUBSTCONST	88		•
SUBSTEMPTY	88		
SUBSTLIST	90		
SUBSTOP	90		

Appendix B

TRACES OF SOLUTIONS

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Appendix B

TRACES OF SOLUTIONS

1. The Maximum of an Array (1)

A complete trace of a proof performed by our system is presented below. The verification condition to be proved is derived from the program to compute the maximal element of an array. Although a proof is contained above in the body of the text, following the trace tells us exactly what rules were applied in the proof. Furthermore, we can see exactly what false starts were made by the system and what user interaction was required to keep the program on the right track.

This particular verification condition was derived from the loop path of the program. The hypotheses are

- 1 (CONTEXT (1 0) 1 0)
- 2 (ASSERT (EQ MAX (ACCESS A LOC)) WRT \$VERICON)
- 3 TRUE
- 4 (ASSERT (LTQ (STRIP (BAGA A 0 I)) MAX) WRT \$VERICON)
- 5 TRUE
- 6 (ASSERT (LTQ 0 LOC) WRT \$VERICON)
- 7 TRUE
- 8 (ASSERT (LTQ LOC I) WRT \$VERICON)
- 3 TRUE
- 10 (ASSERT (LTQ | N) WRT \$VERICON)
- 11 TRUE
- 12 (DENY (LT N (PLUS 1 I)) WRT \$VERICON)
- 13 FLASE
- 14 (DENY (LT MAX (ACCESS A (PLUS 1 I))) WRT SVERICON)
- 15 FLASE

The word "Flase" is a misspelling of "False."

Since the hypotheses for the different verification conditions of a program may contradict each other, each proof is done in a separate context. The name of that context is VERICON. That is the meaning of the

phrase "WRT \$VERICON," which follows our assertions and goal. (For this proof VERICON is ((10) 10).) Assertions made with respect to one VERICON will not affect problems solved with respect to another.

16 (GOAL %PROVE (LTQ (STRIP (BAGA A 0 (PLUS 1 I))) MAX) WRT \$YERICON) 17 LAMBDA PROOFSWITCH (LTQ (STRIP (BAGA A 0 (PLUS 1 I))) MAX)

When a traced function is applied to an argument, the trace says

LAMBDA (function name) (argument) .

Some of the utility functions are not traced.

```
18 (GOAL SINEQUALITIES (SF SX))
19 LAMBDA RELCHECK (LTQ (STRIP (BAGA A Ø (PLUS 1 1))) MAX)
20 LAMBDA PRUOFSIMP (LTQ (STRIP (BAGA A Ø (PLUS 1 1))) MAX)
21 LAMBDA ARGSIMP (LTQ (STRIP (BAGA A Ø (PLUS 1 1))) MAX)
22 LAMBDA SIMPONE (TUPLE (STRIP (BAGA A Ø (PLUS 1 1))) MAX)
(TUPLE (STRIP (BAGA A Ø (PLUS 1 1))) MAX)
SIMPLIFY?
:Y
```

The system asked us whether we wanted it to simplify

(TUPLE (STRIP (BAGA A 0 (PLUS 1 I))) MAX)

We said yes.

```
(GOAL STOPRULES SGOAL1)
             LAMBDA HASSIMP (TUPLE (STRIP (BAGA A Ø (PLUS 1 I))) MAX)
              (FAIL)
             LAMBDA EQNUMB (TUPLE (STRIP (BAGA A 0 (PLUS 1 I))) MAX)
              (FAIL)
            (GOAL $DDWNRULES $GOAL1)
              LAMBDA TUPSIMP (TUPLE (STRIP (BAGA A 0 (PLUS 1 I))) MAX)
                LAMBDA SIMPONE (STRIP (BAGA A 0 (PLUS 1 I)))
(STRIP (BAGA A Ø (PLUS 1 I)))
SIMPLIFY?
: Y
                (GOAL STOPRULES SGOAL1)
31
                  LAMBDA HASSIMP (STRIP (BAGA A 0 (PLUS 1 1)))
32
                  (FAIL)
33
                  LAMBDA EQNUMB (STRIP (BAGA A Ø (PLUS 1 I)))
34
                  (FAIL)
35
                (GOAL $DOWNRULES $GOAL1)
                  LAMBOA ARGSIMP (STRIP (BAGA A Ø (PLUS 1 I)))
37
                    LAMBDA SIMPONE (BAGA A 0 (PLUS 1 I))
(BAGA A Ø (PLUS 1 I))
SIMPLIFY?
: Y
```

```
We have given the system permission to simplify (BAGA A 0 (PLUS 1 I)).
                         (GOAL STOPRULES SGQALI)
     40
                           LAMBDA HASSIMP (BAGA A 0 (PLUS 1 1))
     41
                           (FAIL)
    42
                           LAMBDA BAGAOP (BAGA A Ø (PLUS 1 I))
    43
                           (GOAL #GOALCLASSI #GOAL1)
    44
                             LAMBDA BAGAPLUS (BAGA A 0 (PLUS 1 1))
    45
                             (GOAL &DEOUCE (LTQ &I (PLUS 1 &J)))
The system tries to prove that 0 \le (PLUS 1 I).
     46
                               LAMBOA RELCHECK (LTQ 0 (PLUS 1 1))
     47
                               LAMBDA LTOPLUS (LTQ 0 (PLUS 1 1))
    48
                               (GOAL SDEDUCE (AND (LTQ SI SJ) (LTQ 0 SK)))
    49
                                 LAMBDA RELCHECK (AND (LTQ 0 1) (LTQ 0 1))
It breaks down the goal to 0 \le I and 0 \le 1.
    50
                                 LAMBDA ANDSPLIT (AND (LTQ 0 1) (LTQ 0 1))
    51
                                  (GOAL #GDALCLASS #X)
    52
53
                                   LAMBDA RELCHECK (LTQ 0 1)
                                   RELCHECK = TRUE
     When a function returns a value, the trace says
                         \langle function name \rangle = \langle value \rangle
In this case, the system knew that 0 < 1 by performing the corresponding
LISP evaluation.
    54
                                 (GOAL #GOALCLASS #Y)
                                   LAMBDA RELCHECK (LTQ Ø I)
    55
    56
                                   RELCHECK = TRUE
The 0 \le I follows from hypothesis 8 and 9.
    57
                                 ANDSPLIT = TRUE
                               LTQPLUS = TRUE
    58
    53
                             BAGAPLUS = (BAG (ACCESS A (PLUS 1 I)) (STRIP
    (BAGA A 0 1)))
     The system has succeeded in simplifying
                           (BAGA A 0 (PLUS 1 I))
to
```

(BAG (ACCESS A (PLUS 1 I)) (STRIP (BAGA A O I)))

```
BAGAOP = (BAG (ACCESS A (PLUS 1 I)) (STRIP (BAGA
   ĢΊ
    A 0 1)))
                       SIMPONE = (BAG (ACCESS A (PLUS 1 I)) (STRIP (BAGA
   62
    (((1 B A
                     ARGSIMP = (STRIP (BAG (ACCESS A (PLUS 1 1)) (STRIP
    (BAGA A 0 1))))
                    (GOAL $GOALCLASS $GOAL1)
   64
                     LAMBDA HASSIMP (STRIP (BAG (ACCESS A (PLUS 1 1))
    (STRIP (BAGA A 0 I))))
                      (FAIL)
   66
                     LAMBDA EQNUMB (STRIP (BAG (ACCESS A (PLUS 1 I)) (STRIP
   67
    (BAGA A Ø I))))
   63
                      (FAIL)
                   SIMPONE = (STRIP (BAG (ACCESS A (PLUS 1 I)) (STRIP
    (BAGA A Ø 1))))
                 TUPSIMP = (TUPLE (STRIP (BAG (ACCESS A (PLUS 1 1)) (STRIP
    (BAGA A 0 I))) MAX)
               (GOAL $GOALCLASS $GOAL1)
                 LAMBDA HASSIMP (TUPLE (STRIP (BAG (ACCESS A (PLUS 1 I))
    (STRIP (BAGA A. Ø I)))) MAX)
                 (FAIL)
   73
                 LAMBDA EQNUMB (TUPLE (STRIP (BAG (ACCESS A (PLUS 1 1))
   (STRIP (BAGA A Ø I)))) MAX)
   75
                 (FA]L)
               SIMPONE = (TUPLE (STRIP (BAG (ACCESS A (PLUS 1 I)) (STRIP
   76
   (BAGA A 0 [)))) MAX)
             ARGSIMP = (LTQ (STRIP (BAG (ACCESS A (PLUS 1 1)) (STRIP (BAGA
   77
   A Ø []]]] MAX)
     The problem now is to prove
    (STRIP (BAG (ACCESS A (PLUS 1 I)) (STRIP (BAGA A O I)))) ≤ MAX
   78
           (GDAL $GOALCLASS1 $X)
   79
            LAMBDA RELCHECK (LTQ (STRIP (BAG (ACCESS A (PLUS 1 I)) (STRIP
   (BAGA A Ø I))) MAX)
            RELCHECK = TRUE
But since the system already knows
                     (ACCESS A (PLUS I I)) \leq MAX from (14),
and
                    (STRIP (BAGA A 0 I)) \leq MAX from (4) ,
the proof is complete:
          PROOFSIMP = TRUE
   81
         (ASSERT (SF $X))
   82
        PROOFSWITCH = (LTQ (STRIP (BAGA A 0 (PLUS 1 I))) MAX)
   84 (LTQ (STRIP (BAGA A 0 (PLUS 1 I))) MAX)
```

(GOAL \$GOALCLASSI \$GOAL1)

60

The Maximum of an Array (2)

The following is the trace of the proof for another verification condition for the program that computes the maximal element of an array.

This verification condition is derived from the halt path of the program.

- 1 (COMPEXT (1.0) 1.0)
- 2 (ASSERT (EQ MAX (ACCESS A LOC)) WRT #VERICON)
- 3 TRUE
- 4 (ASSERT (LTQ (STRIP (BAGA A 0 1)) MAX) WRT \$VERICON)
- 5 TRUE
- 6 (ASSERT (LTQ 0 LOC) WRT \$VERICON)
- 7 TRUE
- 8 (ASSERT (LTQ LOC 1) WRT \$VERICON)
- 9 TRUE
- 10 (ASSERT (LTQ I N) WRT \$VERICON)
- 11 TRUE
- 12 (ASSERT (LT N (PLUS 1 1)) WRT #VERICON)

There is a demon that knows that in the integer domain,

$$x < y \supset x+1 \le y$$

This demon is responsible for the assertion

13 (ASSERT (LTQ (PLUS 1 \$X) \$Y) WRT \$VERICON)

The system now knows $N+1 \le I+1$. This assertion wakes up another demon:

- 14 (ASSERT (LTQ BY BZ) WRT BYERICON)
- 15 TRUC

The system now knows that $N \le I$. Since $I \le N$ has just been asserted (5), the mechanism for storing ordering relations silently tells the system that I = N.

The system proceeds with the proof:

```
16 (GUAL SPECVE (LTQ-(STRIP (BAGA A 0 N)) (ACCESS A LOC)) WRT $VERICON)
     LAMBDA PROOFSWITCH (LTG (STRIP (BAGA A 0 N)) (ACCESS A LOC))
17
1 .
     (GOAL $IMEQUALITIES ($F $X))
       LAMBDA BELCHECK (LTO (STRIP (BAGA A 0 N)) (ACCESS A LOC))
13
20
21
22
       LANDOA PROUESIME (LTQ (STRIP (BAGA A 0 N)) (ACCESS A LOC))
         FAMBDA ARGSIMP (LTQ (STRIP (BAGA A 0 N)) (ACCESS A LOC))
           LAMBDA SIMPONE (TUPLE (STRIP (BAGA A 8 N)) (ACCESS A LOC))
(TUPLE (STRIP (BAGA A R N)) (ACCESS A LOCI)
SHIPLIEY?
100456
10026
            (FAIL)
        (FAIL)
       LAMBDA PROOFLEIB (LTQ (STRIP (BAGA A 8 N)) (ACCESS A LOC))
       (EX1STS ($F ←Y))
```

The system searches the data base for an assertion of the form (LTQ \leftarrow Y), i.e., the gross form of the goal we are trying to prove. It finds one [assertion (2)] and asks us if it should try to prove that the argument of the assertion it has found is equal to the argument of the goal:

(EQ (TUPLE (STRIP (BAGA A 0 N)) (ACCESS A LOC)) (TUPLE (STRIP (BAGA A 0 I)) MAX))
PROVE?

We say yes, and the proof proceeds.

```
:7
27 (GOAL $EQRULES (EQ $X $Y))
28 LAMBDA RELCHECK (EQ (TUPLE (STRIP (BAGA A Ø N)) (ACCESS A LOC)) (TUPLE (STRIP (BAGA A Ø I)) MAX))
29 RELCHECK = TRUE
30 PROUBLEID = TRUE
31 (ASSERT ($F $X))
32 PROUBSNITCH = (LTQ (STRIP (BAGA A Ø N)) (ACCESS A LOC))
33 (LTQ (STRIP (BAGA A Ø N)) (ACCESS A LOC))
```

The two tuples were found to be equal because N = I (from 10 and 14), and MAX = A[LOC]. The proof is complete.

2. The Wensley Division Algorithm

The following is the complete trace of the proof included in the body of the text:

```
1 (CONTEXT (1 0) 1 0)
2 (ASSERT (EQ AA (TIMES QQ YY)) WRT $VERICON)
3 LEUE
4 (ASSERT (EQ (TIMES 2 8B) (TIMES QQ QD)) WRT $VERICON)
5 FRUE
6 (ASSERT (LT PP (PLUS (TIMES QQ YY) (TIMES QQ DD))) WRT $VERICON)
7 TRUE
8 (ASSERT (LTQ (TIMES QQ YY) PP) WRT $VERICON)
9 TRUE
10 (ASSERT (LT PP (PLUS AA BB)) WRT $VERICON)
11 TRUE
12 (DEUY (LT (DIVIDES DQ 2) EE) WRT $VERICON)
13 CALSE
```

The goal is to prove PP < QQ*YY + QQ*(DD/2):

```
14 (QOAL MPROVE (LT PP (PLUS (TIMES QQ YY) (TIMES QQ (DIVIDES DD 2))))
MRI SVERICOND
    LAMPOA PRODESWITCH (LT PP (PLUS (TIMES QQ YY) (TIMES QQ (DIVIDES
15
00 2000
     (GOAL $1NEQUALITIES ($F $X))
16
       LAMBDA RELCHECK (LT PP (PLUS (TIMES OQ YY) (TIMES QQ (DIVIDES
17
DD 21111
       LAMBDA PROOFSIMP (LT PP (PLUS (TIMES QQ YY) (TIMES QQ (DIVIDES
18
[四 2]])))
         LAMBDA ARGSIMP (LT PP (PLUS (TIMES QQ YY) (TIMES QQ (DIVIDES
19
ונננג סס
           LAMBDA SIMPONE (TUPLE PP (PLUS (TIMES QQ YY) (TIMES QQ
^{\circ}G
(UIVIDES DD 2))))
             LAMBDA ASK (TUPLE (TUPLE PP (PLUS (TIMES QQ YY) (TIMES
21
od (MIVIDES DD 2000) SIMPLIFY?)
(TUPLE PP (PLUS (TIMES QQ YY) (TIMES QQ (QIVIDES DD 2))))
SIMPLIEY?
:140
              (FAIL)
       (FAIL)
       LAMBDA PRODFLEIB (LT PP (PLUS (TIMES QQ YY) (TIMES QQ (DIVIDES
24
DD 2000
25
       (EXISTS (8F ~Y))
         LAMBDA ASK (TUPLE (EQ (TUPLE PP (PLUS (TIMES QQ YY) (TIMES
ng (pivipes po 2)))) (TUPLE PP (PLUS (TIMES QQ YY) (TIMES QQ DD))))
(EQ (TUPLE PP (PLUS (TIMES QQ YY) (TIMES QQ (DIVIDES DD 2)))) (TÜPLE
PP (PLUS (TIMES QQ YY) (TIMES QQ DD))))
FROVE?
:140
```

```
27
23
                (FAIL)
               LAMPDA ASK (TUPLE (EQ (TUPLE PP (PLUS (TIMES QQ YY) (TIMES
      OG (DIVIDES DD 2)))) (TUPLE PP (PLUS AA BB))) PROVE?)
      (EQ (TUPLE PP (PLUS (TIMES QQ YY) (TIMES QQ (DIVIDES DD 2)))) (TUPLE
      EP (PLUS AA 8B)))
      FROVE?
      : NO
      20
                (FAIL)
             LAMODA INEQLEIB (LT PP (PLUS (TIMES QQ YY) (TIMES QQ (DIVIDES
      ୍ଦର
      DO 2000
      31
             (EXTRIS (%L (TUPLE -LOWER -UPPER)))
               LAMEDA ASK (TUPLE PROVE (LTQ PP PP) AND (LTQ (PLUS (TIMES
      na YY) (TIMES NG ND)) (PLUS (TIMES NG YY) (TIMES QQ (DIVIDES ND 2))))
      2)
      PERME
      (L))) PP (PP)
      (LTQ (PLUS (TIMES QQ YY) (TIMES QQ DD)) (PLUS (TIMES QQ YY) (TIMES
      CO COLVINES DO STEEL
After several false starts the system reaches using hypothesis (10), it
generates two subgoals: PP \leq PP and AA + BB \leq QQ*YY + QQ*(DD/2). We
give our approval of this tactic:
     一:160
      33
                (FAIL)
               LAMEDA ASK (TUPLE PROVE (LTQ FP FP) AND (LTQ (PLUS AA BB)
      (PLUS (TIMES DO YY) (TIMES QQ (DIVIDES DD 2)))) ?)
      PROVE
      (LTG PP PP)
      ANE
      (LIQ (PLUS AA BB) (PLUS (TIMES QQ YY) (TIMES QQ (DIVIDES DD 2))))
      : YES
                ASK = TRUE
      35
It proves the first subgoal immediately.
      36
              (QUAL $INEQUALITIES (AND (LTQ $X $LOWER) (LTQ $UPPER $Y))) .
      37
                LAMPDA ANDSPLIT (AND (LTQ PP PP) (LTQ (PLUS AA BB) (PLUS
      (TIMES ON YY) (TIMES ON (DIVIDES OD 2)))))
      33
                (GOAL BROALCLASS BX)
      39
                  LAMBOA RELCHECK (LTQ PP PP)
      48
                  RELCHECK = TRUE
                (GOAL $GOALCLASS (AND $8Y))
      41
                  LAMBDA ANDSPLIT (AND (LTQ (PLUS AA BB) (PLUS (TIMES QQ
      YY) (TIMES OR (DIVIDES OD 2)))))
      43
                  (GOAL $GOALCLASS $X)
                    LAMBDA RELCHECK (LTQ (PLUS AA BB) (PLUS (TIMES QQ YY)
      (TIMES QQ (DIVIDES DD 2))))
                    LAMBDA INECMONOTONE (LTQ (PLUS AA BB) (PLUS (TIMES QQ
      YY) (TIMES OO (DIVIDES DD 2))))
                      LAMBDA ASK (TUPLE ((LTQ AA (TIMES QQ (DIVIDES DD 2)))
      (LIQ PB (IIDLS QQ YY))) PROVE?)
      (UTO AA (TIMES OO (DIVIDES DD 2))) (LTQ 88 (TIMES QD YY)))
      PRUVE?
      : 140
```

```
47 (FAIL)
48 LAMPDA INEQMONOTONE (LTQ (PLUS AA BB) (PLUS (TIMES QQ YY)) (TIMES QQ (DIVIDES OD 2))))
49 LAMBDA ASK (TUPLE ((LTQ AA (TIMES QQ YY)) (LTQ BB (TIMES QQ (UIVIDES OD 2)))) PROVE?)
((LTQ AA (TIMES QQ YY)) (LTQ BB (TIMES QQ (DIVIDES DD 2))))
PROVE?
```

It divides the second subgoal into two subsubgoals: AA \leq QQ*YY and BB < QQ*(DD/2):

The first subsubgoal follows from hypothesis (2).

```
56
                  (GOAL $GOALCLASS (AND $$Y))
57
                    LAMBDA ANDSPLIT (AND (LTQ BB (TIMES QQ (DIVIDES DD
21111
\mathbf{U}_{i}\mathbf{S}_{i}
                     (GOAL #GOALCLASS #X)
5.3
                       LAMBDA RELCHECK (LTQ BB (TIMES QQ (DIVIDES DD 2)))
                       LAMBDA INEQTIMESDIVIDE (LTQ BB (TIMES QQ (DIVIDES
\mathbf{E}(\mathbf{G})
DD 2111
                       (GDAL SDEDUCE (LT Ø SY))
61
\mathbb{R}^{2}
                         LAMBDA RELCHECK (LT 0 2)
G3
                         RELCHECK = TRUE
                       (GOAL BINEQUALITIES (SF (TUPLE (TIMES BY SW) (TIMES
66
9M 982}}}
65
                         LAMBDA RELCHECK (LTQ (TIMES 2 BB) (TIMES QQ DD))
                         RELUHECK = TRUE
66
```

Checking that 2 > 0, the system multiplied out the second subgoal into $2*BB \le QQ*DD$. This follows from assertion (4). The proof is complete:

```
INEQTIMESDIVICE = TRUE
67
                   (GOAL $GOALCLASS (AND $$Y))
68
                  ANDSPLIT = (AND)
15.3
                ANDSPLIT = (AND)
7A
              INEQHONOTONE = (AND)
71
            (GCIAL #GDALDLASS (AND ##Y))
            ANDSPLIT = (AND)
          AMOSPLIT = (AND)
74
75
        INEQLEIB = (AND)
     (ASSERT (SF $X))
76
77
     (RETURN ($F $X))
78
     PRODESMITCH = (LT PP (PLUS (TIMES QQ YY) (TIMES QQ (DIVIDES DD
21111
79 (LT PP (PLUS (TIMES QQ YY) (TIMES QQ (DIVIDES DD 2))))
```

```
3.
     The Pattern Matcher
     As an abbreviation, let
                    m1 = match(car(pat), car(arg))
and
             m2 = match(varsubst(ml, cdr(pat)), cdr(arg))
The hypotheses are that
                  varsubst(ml, car(pat)) = car(arg) ;
or in unabbreviated form,
   1 (ASSERT (EQ (VARSUBST (MATCH (CAR PAT) (CAR ARG)) (CAR PAT)) (CAR
    ARG)))
    2 TRUE
and that
           varsubst(m2, varsubst(m1, cdr(pat))) = cdr(arg)
    3 (ASSERT (EQ (VARSUBST (MATCH (VARSUBST (MATCH (CAR PAT) (CAR ARG)))
    (CDR ('AT)) (CDR ARG)) (VARSUBST (MATCH (CAR PAT) (CAR ARG)) (CDR PAT)))
    (CDR ARG)))
    4 TRUE
    The other hypotheses are
      (ASCERT (CONSTEXP ARG))
    6 TRUE
    7
       (ASSERT (NOT (CONST PAT)))
    8 TRUE
    9 (ASSERT (NOT (ATOM ARG)))
    10 TRUE
    11 (ASSERT (NOT (VAR PAT)))
    12 TRUE
    The goal is to prove
                 varsubst(compose(m2, m1), pat) = arg :
```

13 (GDAL MPROVE (EQ (VARSUBST (COMPOSE (MATCH (VARSUBST (MATCH (CAR PAT) (CAR ARG)) (CDR PAT)) (CDR ARG)) (MATCH (CAR PAT) (CAR ARG)))

PAID ARGOD

The proof begins:

```
LAMBDA PROOFSULTCH (EQ (VARSUBST, (CONPOSE (MATCH (VARSUBST (MATCH
(CAR PAT) (CAR ARG)) (CDR PAT)) (CDR ARG)) (MATCH (CAR PAT) (CAR ARG)))
PAID ARG)
15
      (GOAL #EORULES (#F #X))
       LAMBDA RELCHECK (EQ (VARSUBST (COMPOSE (MATCH (VARSUBST (MATCH
(CAR PAI) (CAR ARG)) (CDR PAI)) (CDR ARG)) (MATCH (CAR PAI) (CAR ARG)))
PAT) ARG)
       LAMBUA EQSUBST (EQ (VARSUBST (COMPOSE (MATCH (VARSUBST (MATCH
(CAR PAT) (CAR ARG)) (CDR PAT)) (CDR ARG)) (MATCH (CAR PAT) (CAR ARG)))
PAT) ARG)
18
        (GOAL #EQSUBSTRULES #Y)
         LAMBDA SUBSTOONS (EQ (VARSUBST (COMPOSE (MATCH (VARSUBST
13
(MATCH (CAR PAT) (CAR ARG)) (COR PAT)) (COR ARG)) (MATCH (CAR PAT)
(CAR ARG))) PAT) ARG)
20
21
22
23
          (GOAL $DEDUCE (NOT (ATOM $X)))
           LAMBOA RELCHECK (NOT (ATOM PAT))
           LAMBEA NOTATOM (NOT (ATOM PAT))
            (EXISTS (NOT (VAR $X)))
24
            (EXISTS (NOT (CDNST $X)))
25
           NOTATOM = (NOT (CONST PAT))
26
          (GOAL SCIEDUCE (NOT (ATOM $Y)))
         (GOAL, (= ($REMOVE (TUPLE EQSUBST FROM $EQRULES))) (EQ (YARSUBST
$$1 (CAR $X)) (CAR $Y)))
```

Reasoning that pat is not an atom since it is neither a variable nor a constant, the system breaks the goal into two subgoals:

```
varsubst (compose(m2, m1), car(pat)) = car(arg)
```

and

varsubst (compose(m2, m1), cdr(pat)) = cdr(arg)

It begins work on the first of these:

```
LAMBOA RELCHECK (EQ (CAR ARG) (VARSUBST (COMPOSE (MATCH (VARSUBST (MATCH (CAR PAT) (CAR ARG)) (COR PAT)) (CDR ARG)) (MATCH (CAR PAT) (CAR ARG)) (CAR ARG)) (COR PAT)) (CDR ARG)) (MATCH (CAR PAT) (CAR ARG)) (COR PAT)) (CDR ARG)) (MATCH (CAR PAT) (CAR ARG)) (CAR PAT))

BY LAMBOA EQSIMP (EQ (CAR ARG) (VARSUBST (COMPOSE (MATCH (VARSUBST (MATCH (CAR PAT) (CAR ARG))) (CAR PAT))

CAR PAT) (CAR ARG)) (CDR PAT)) (CDR ARG)) (MATCH (CAR PAT) (CAR ARG)) (CDR PAT)) (CDR ARG)) (MATCH (CAR PAT) (CAR ARG)) (CDR PAT)) (CDR ARG)) (MATCH (CAR PAT)) (CDR ARG)) (MATCH (CAR PAT)) (CDR ARG)) (MATCH (CAR PAT)) (CDR PAT))
```

We give the system our permission to simplify the left side of the first

varsubst (compose(m2, ml), car(pat))

```
(GOAL STOPRULES $GOAL1)
31
32
                LAMBDA HASSIMP (VARSUBST (COMPOSE (MATCH (VARSUBST
(MATCH (CAR PAT) (CAR ARG)) (COR PAT)) (COR ARG)) (MATCH (CAR PAT)
(CAR ARG))) (CAR PAT))
                (FAIL)
33
                LAMBDA SUBSTOP (VARSUBST (COMPOSE (MATCH (VARSUBST
34
(MATCH (CAR PAT) (CAR ARG)) (COR PAT)) (COR ARG)) (MATCH (CAR PAT)
(CAR ARG))) (CAR PAT))
35
                (GOAL $SUBSTRULES $Y)
                  LAMBDA SUBSTCOMPOSE (VARSUBST (COMPOSE (MATCH (VARSUBST
36
(MATCH (CAR PAT) (CAR ARG)) (CDR PAT)) (CDR ARG)) (MATCH (CAR PAT)
(CAR ARG))) (CAR PAT))
                  (GOAL #GOALCLASS #GOAL1)
37
                    LAMBDA SUBSTCONST (VARSUBST (MATCH (VARSUBST (MATCH
38
(CAR PAT) (CAR ARG)) (CDR PAT)) (CDR ARG)) (VARSUBST (MATCH (CAR PAT)
(CAR ARG)) (CAR PAT)))
                    (GDAL $OEDUCE (CONSTEXP $Y))
39
                      LAMBDA RELCHECK (CONSTEXP (VARSUBST (MATCH (CAR
40
PAT) (CAR ARG)) (CAR PAT)))
                  SUBSTOOMPOSE = (VARSUBST (MATCH (VARSUBST (MATCH
(CAR MAT) (CAR ARG)) (CDR PAT)) (CDR ARG)) (VARSUBST (MATCH (CAR MAT)
(CAR ARG)) (CAR PAT)))
                SUBSTOP = (VARSUBST (MATCH (VARSUBST (MATCH (CAR PAT)
(CAR ARG)) (CDR PAT)) (CDR ARG)) (VARSUBST (MATCH (CAR PAT) (CAR ARG))
(CAR PAT)))
              (RETURN $SIMPGOAL)
43
              SIMPONE = (VARSUBST (MATCH (VARSUBST (MATCH (CAR PAT)
44
(CAR ARG)) (CDR PAT)) (CDR ARG)) (VARSUBST (MATCH (CAR PAT) (CAR ARG))
((AR FAT)))
```

The system has succeeded in simplifying the left half of the goal into

varsubst(m2, varsubst(ml, car(pat)))

It now tries to prove this new expression equal to car(arg):

```
45 (GOAL #EQRULES (EQ #X #Y))
46 LAMBDA RELCHECK (EQ (CAR ARG) (VARSUBST (MATCH (VARSUBST (MATCH (CAR ARG)) (CAR ARG)) (CDR PAT)) (CDR ARG)) (VARSUBST (MATCH (CAR PAT) (CAR ARG)) (CAR PAT)))
47 LAMBDA EOSUBST (EQ (CAR ARG) (VARSUBST (MATCH (VARSUBST (MATCH (CAR PAT) (CAR ARG)) (COR PAT)) (CDR ARG)) (VARSUBST (MATCH (CAR PAT) (CAR ARG)) (CAR PAT))))
48 (GOAL #EOSUBSTRULES #Y)
49 LAMBDA SUBSTCONS (EO (CAR ARG) (VARSUBST (MATCH (VARSUBST (MATCH (CAR PAT) (CAR ARG)) (COR PAT)) (COR ARG)) (VARSUBST (MATCH (CAR PAT) (CAR ARG)) (COR PAT)))
50 (GOAL #DEOUGE (NOT (ATOM #X)))
```

```
51
                 LAMBDA RELUHECK (NOT (ATOM (VARSUBST (MATCH (CAR
PAI) (CAR ARG)) (CAR PAI))))
                 LANCOA NOTATOM (NOT (ATOM (YARSUBST (MATCH (CAR PAT)
(CAR ARG)) (CAR PAT))))
                  (EXISTS (NOT (VAR $X)))
53
54
             LAMBOA EOSIMP (EO (CAR ARG) (MARSUBST (MATCH (MARSUBST
(MATCH (CAR FAT) (CAR ARG)) (CDR FAT)) (COR ARG)) (VARSUBST (MATCH
(CAR PAI) (CAR ARG)) (CAR PAI))))
               LAMBDA SIMPONE (VARSUBST (MATCH (VARSUBST (MATCH (CAR
PAI) (CAR ARG)) (CDR PAI)) (COR ARG)) (VARSUBSI (MATCH (CAR PAI) (CAR
ARG)) (CAR FAT)))
(VARSUBST (MATCH (VARSUBST (MATCH (CAR PAT) (CAR ARG)) (CDR PAT))
(COR ARG)) (VARSUBST (MATCH (CAR PAT) (CAR ARG)) (CAR PAT)))
SHIPLIFY?
```

The system asks permission to simplify

varsubst(m1, varsubst(m2, car(pat)))

further. Permission is granted:

```
: Y
\mathbb{R}^{C}
                 (GDAL $TOPRULES $GDAL1)
                  LAMBDA HASSIMP (YARSUBST (MATCH (YARSUBST (MATCH
(CAR PAT) (CAR ARG)) (CDR PAT)) (CDR ARG)) (VARSUBST (MATCH (CAR PAT)
(CAR ARG)) (CAR PAT)))
58
                   (FAIL)
50
                  LAMBDA SUBSIDE (MARSUBST (MATCH (MARSUBST (MATCH
(CAR PAT) (CAR ARG)) (CDR PAT)) (CDR ARG)) (VARSUBST (MATCH (CAR PAT)
(CAR ARG)) (CAR PAT)))
                  (GOAL $SUBSTRULES $Y)
\{\cdot, \{\}\}
                    LAMBDA SUBSTCONST (VARSUBST (MATCH (VARSUBST (MATCH
G1
(CAR PAT) (CAR ARG)) (CDR PAT)) (CDR ARG)) (VARSUBST (MATCH (CAR PAT)
(CAR ARG)) (CAR PAT)))
                     (GDAL $DEDUCE (CONSTEXP $Y))
62
                      LAMBDA RELCHECK (CONSTEXP (VARSUBST (MATCH (CAR
63
PAT) (CAR ARG)) (CAR PAT)))
                  LAMBDA EQNUMB (VARSUBST (MATCH (VARSUBST (MATCH (CAR
PAT) (CAR ARG)) (CDR PAT)) (CDR ARG)) (VARSUBST (MATCH (CAR PAT) (CAR
ARG)) (CAR PAT)))
65
                   (FAIL)
\mathbb{C} \mathbb{C}
                 (GOAL $DOWNRULES $GOAL1)
                  LAMBDA ARGSIMP (VARSUBST (MATCH (VARSUBST (MATCH
(CAR PAT) (CAR ARG)) (CDR PAT)) (CDR ARG)) (VARSUBST (MATCH (CAR PAT)
(CAR ARG)) (CAR PAT)))
                    LAMBDA SIMPONE (TUPLE (MATCH (VARSUBST (MATCH (CAR
PAT) (CAR ARG)) (CDR PAT)) (CDR ARG)) (VARSUBST (MATCH (CAR PAT) (CAR
ARG)) (CAR PAT)))
(TUPLE (MATCH (VARSUBST (MATCH (CAR PAT) (CAR ARG)) (COR PAT)) (COR
ARG)) (VARSUBST (MATCH (CAR PAT) (CAR ARG)) (CAR PAT)))
SIMPLIFY?
: Y
                     (GDAL $TOPRULES $GDAL1)
69
                      LAMBDA HASSIMP (TUPLE (MATCH (VARSUBST (MATCH
(CAR PAT) (CAR ARG)) (CDR PAT)) (CDR ARG)) (VARSUBST (MATCH (CAR PAT)
(CAR ARG)) (CAR PAT)))
```

```
71
                      (FAIL)
                      LAMBDA EDNUMB (TUPLE (MATCH (VARSUBST (MATCH
72
(CAR PAT) (CAR ARG)) (CDR PAT)) (CDR ARG)) (VARSUBST (MATCH (CAR PAT)
(CAR ARG)) (CAR PAT)))
                      (FAIL)
73
                    (GOAL $DOWNRULES $GOAL1)
74
                      LAMBDA TUPSIME (TUPLE (MATCH (VARSUBST (MATCH
75
(CAR PAT) (CAR ARG)) (CDR PAT)) (CDR ARG)) (VARSUBST (MATCH (CAR PAT)
(CAR ARG)) (CAR PAT)))
                        LAMBDA SIMPONE (MATCH (VARSUBST (MATCH (CAR
76
PAT) (CAR ARG)) (CDR PAT)) (CDR ARG))
(MATCH (VARSUBST (MATCH (CAR PAT) (CAR ARG)) (CDR PAT)) (CDR ARG))
SIMPLIFY?
: N
77
                        (FAIL)
                      LAMBDA TUPSIMP (TUPLE (MATCH (VARSUBST (MATCH
(CAR PAT) (EAR ARG)) (CDR PAT)) (CDR ARG)) (VARSUBST (MATCH (CAR PAT)
(CAR ARG)) (CAR PAT)))
                        LAMBDA SIMPONE (VARSUBST (MATCH (CAR PAT) (CAR
73
ARG)) (CAR PAT))
(VARSUBST (MATCH (CAR PAT) (CAR ARG)) (CAR PAT))
SIMPLIFY?
```

The system wants to simplify varsubst(ml, car(pat)), a subexpression of our goal. We give our blessings:

```
: Y
                         (GDAL $TOPRULES &GOAL1)
93
                          LAMBDA HASSIMP: (VARSUBST (MATCH (CAR PAT)
31
(CAR ARG)) (CAR PAT))
                           (FAIL)
                          LAMBDA SUBSTOP (VARSUBST (MATCH (CAR PAT)
83
(CAR ARG)) (CAR FAT))
                           (GDAL $SUBSTRULES $Y)
84
                             LAMBDA SUBSTECINST (VARSUBST (MATCH (CAR
85
PAT) (CAR ARG)) (CAR PAT))
                             (GOAL SDEDUCE (CONSTEXP SY))
                               LAMBDA RELUHECK (CONSTEXP (CAR PAT))
87
                               LAMBDA CONSTCAR (CONSTEXP (CAR PAT))
88
                               (EXISTS (CONSTEXP $X))
CS
                          LAMBDA EQNUMB (VARSUBST (MATCH (CAR PAT)
(CAR ARG)) (CAR PAT))
                           (RETURN SBEST)
91
                           EQNUMB = (CAR ARG)
92
                         (RETURN $SIMPGOAL)
93
                         SIMPONE = (CAR ARG)
94
```

The subexpression varsubst(ml, car(pat)) is known to be equal to car(arg) by hypothesis (1). The rule EQNUMB has found this simplification. Work continues on simplifying the entire left-hand side.

```
TURSINE = (TUPLE (MATCH (VARSUBST (MATCH (CAR
PALL (CAR ARG)) (CDR PAIL) (CDR ARG)) (CAR ARG))
                     (GOAL $60AUCLASS $60AL1)
                      LAMBOA HASSIME CTUPLE (MATCH (VARSUBST (MATCH
(CAR MAI) (CAR ARGI) (CDR MAI)) (CDR ARGI) (CAR ARGI)
98
                       (FAIL)
C^{\prime}
                      LAMBDA FONUMB (TUPLE (MATCH (VARSUBST (MATCH
(CAR PAT) (CAR ARG)) (CDR PAT)) (CDR ARG)) (CAR ARG))
                       (FAIL)
                     (RETURN $SIMPGOAL)
101
                    SIMPONE = (TUPLE (MATCH (VARSUBST (MATCH (CAR PAT)
100
(CAR ARG)) (CDR PAT)) (CDR ARG)) (CAR ARG))
                  ARGSIMP = (VARSUUST (MATCH (VARSUUST (MATCH (CAR
PAT) (CAR ARG)) (CDR PAT)) (CDR ARG)) (CAR ARG)) -
```

The expression being simplified is now varsubst(m2, car(arg)):

```
104
                 (GDAL #GOALELASS #GDAL1)
105
                  LAMBDA HASSIMP (VARSUBST (MATCH (VARSUBST (MATCH
(CAR PAT) (CAR ARG)) (CDR PAT)) (CDR ARG)) (CAR ARG))
106
                   (FAIL)
197
                  LAMBDA SUBSTOP (VARSUBST (MATCH (VARSUBST (MATCH
(CAR PAT) (CAR ARG)) (CDR PAT)) (CDR ARG)) (CAR ARG))
                   (GOAL $SUBSTRULES $Y)
103
                    LAMBDA SUBSTCORST (VARSUBST (MATCH (VARSUBST (MATCH
(CAR PAT) (CAR ARG)) (CDR (AT)) (CDR ARG)) (CAR ARG))
110
                    (GOAL $0EOUCE (CONSTEXP $Y))
111
                      LAMBDA RELCHECK (CONSTEXP (CAR ARG))
112
                      LAMBDA CONSTCAR (CONSTEXP (CAR ARG))
113
                      (EXISTS (CONSTEXP $X))
114
                      CONSTEAR = (CONSTEXP ARG)
115
                    SUBSTCONST ≈ (CAR ARG)
116
                  SUBSTOP = (CAR ARG)
117
                (RETURN $SIMPGOAL)
118
                SIMPONE = (CAR ARG)
```

Since arg consists entirely of constants, so does car(arg). Therefore, substitutions have no effect on car(arg), and the left-hand side of our subgoal reduces to car(arg) itself, which is precisely the same as the right-hand side.

```
119 (GOAL SEQRULES (EQ $X $Y))
120 LAMEDA RELCHECK (EQ (CAR ARG))
121 RELCHECK = TRUE
122 EQSIMP = TRUE
123 EQSIMP = TRUE
```

We have yet to prove the second subgoal:

```
varsubst (compose(m2, m1), cdr(pat)) = cdr(arg)
```

```
LAMBDA RELCHECK (EQ (CDR ARG) (VARSUBST (CDMPOSE (MATCH
   (VARSUBST (MATCH (CAR PAT) (CAR ARG)) (CDR PAT)) (CDR ARG)) (MATCH
   (CAR PAT) (CAR ARG))) (CDR PAT)))
              LAMBDA EQSIMP (EQ (COR ARG) (VARSUBST (COMPOSE (MATCH (
  VARSUBST (MATCH (CAR PAT) (CAR ARG)) (CDR PAT)) (CDR ARG)) (MATCH
   (CAR PAT) (CAR ARG))) (CDR PAT)))
                LAMBDA SIMPONE (VARSUBST (COMPOSE (MATCH (VARSUBST (MATCH
   (CAR PAT) (CAR ARG)) (CDR PAT)) (CDR ARG)) (MATCH (CAR PAT) (CAR ARG)))
   (CDR PAT))
   (VARSUBST (COMPOSE (MATCH (VARSUBST (MATCH (CAR PAT) (CAR ARG)) (CDR
  PAT)) (CDR ARG)) (MATCH (CAR PAT) (CAR ARG))) (CDR PAT))
  SIMPLIFY?
  : Y
  128
                (GDAL STOPRULES SGDAL1)
                  LAMBOA HASSIMP (VARSUBST (COMPOSE (MATCH (VARSUBST
   (HATCH (CAR PAT) (CAR ARG)) (CDR PAT)) (CDR ARG)) (MATCH (CAR PAT)
   (CAR ARG))) (CDR PAT))
  130
                  (FAIL)
                  LAMEDA SUBSTOP (VARSUBST (COMPOSE (MATCH (VARSUBST
  131
   (MATCH (CAR PAT) (CAR ARG)) (CDR PAT)) (CDR ARG)) (MATCH (CAR PAT)
   (CAR ARG))) (CDR PAT))
                  (GDAL $SUBSTRULES $Y)
  132
  133
                    LAMBDA SUBSTCDMPOSE (VARSUBST (COMPOSE (MATCH (VARSUBST
   (MATCH (CAR PAT) (CAR ARG)) (CDR PAT)) (CDR ARG)) (MATCH (CAR PAT)
   (CAR ARG))) (CDR PAT))
                     (GDAL #GDALCLASS #GGALI)
   134
                      LAMBDA SUBSTCONST (VARSUBST (MATCH (VARSUBST (MATCH
   135
   (CAR PAT) (CAR ARG)) (CDR PAT)) (CDR ARG)) (VARSUBST (MATCH (CAR PAT)
   (CAR ARG)) (COR PAT)))
                       (GDAL SDEDUCE (CONSTEXP SY))
   136
                        LAMBDA RELCHECK (CONSTEXP (VARSUBST (MATCH (CAR
  PAT) (CAR ARG)) (COR PAT)))
                    SUBSTCOMPOSE = (VARSUBST (MATCH (VARSUBST (MATCH
   (CAR PAT) (CAR ARG)) (CDR PAT)) (CDR ARG)) (VARSUBST (MATCH (CAR PAT)
   (CAR ARG)) (CDR PAT)))
                  SUBSTOP = (VARSUBST (MATCH (VARSUBST (MATCH (CAR PAT)
   133
   (CAR ARG)) (CDR PAT)) (CDR ARG)) (VARSUBST (MATCH (CAR PAT) (CAR ARG))
   (CUR PAT)))
                 (RETURN $SIMPGDAL)
  149
                SIMPONE = (VARSUBST (MATCH (VARSUBST (MATCH (CAR PAT)
  141
   (CAR ARG)) (CDR PAT)) (CDR ARG)) (VARSUBST (MATCH (CAR PAT) (CAR ARG))
   (COR PAT)))
The subgoal has been simplified to
              varsubst(m2, varsubst(m1, cdr(pat))) = cdr(arg)
However, this is precisely our hypothesis (3).
               (GOAL SEQRULES (EQ $X $Y))
   142
              EDSIMP = (EQ (VARSUBST (MATCH (VARSUBST (MATCH (CAR PAT)
   143
   (CAR ARG)) (CDR PAT)) (CDR ARG)) (VARSUBST (MATCH (CAR PAT) (CAR ARG))
   (CUR PATI)) (COR ARG))
```

(GDAL (= (\$RENGVE (TUPLE EQSUBST FROM \$EQRULES))) (EQ (VARSUBST

\$51 (CDR \$X)) (CDR \$Y)))

```
SUBSTRUMES -- (EO (VARSUBST (MATCH (VARSUBST (MATCH (CAR PAT) (CAR ARG)) (COR ARG)) (MATCH (CAR ARG)) (COR ARG)) (COR ARG)) (MATCH (CAR ARG)) (COR ARG)) (
```

The proof is complete.

4. FIND

Only a selection from the trace for the interesting verification condition of FIND is presented here because of the length of the entire trace. We will focus on the use of the case analysis during the proof.

The antecedent hypotheses for this condition are

```
1 \leq M \leq F \leq NN
M \leq I
J \leq N
(STRIP (BAGA A I M-1)) \leq (STRIP (BAGA A M NN))
(STRIP (BAGA A 1 N)) \leq (STRIP (BAGA A N+1 NN))
(STRIP (BAGA A 1 I-1)) \leq R
R \leq (STRIP (BAGA A 1+J NN))
A[J] \leq R
R \leq A[I]
I \leq J
J-1 < I+1
F \leq J-1
```

The theorem to be proved is

(STRIP (BAGA (EXCHANGE A I J) 1 J-1))
≤ (STRIP (BAGA (EXCHANGE A I J) (J-1)+1 NN)

This goal is simplified to

(IF J-1 < I THEN (STRIP (BAGA A 1 J-1))

ELSE (STRIP (BAG (STRIP (BAGA A 1 I-1))
A[J]

(STRIP (BAGA A I+1 J-1))))

 \leq (IF J \leq I THEN (BAGA A J NN)

ELSE (STRIP (BAG A[I]

(STRIP (BAGA A J+1 NN))

(STRIP (BAGA A J J-1))))) :

1 (GOAL SIMEQUALITIES (LTQ (IFTHENELSE (LT (SUBTRACT J 1) 1) (STRIP (BAGA A 1 (SUBTRACT J 1))) (STRIP (BAGA A 1 (SUBTRACT J 1))) (ACCESS A J) (STRIP (BAGA A (PLUS 1 I) (SUBTRACT J 1))))) (IFTHERICSE (LTQ J 1) (STRIP (BAGA A J NN)) (STRIP (BAGA A J (SUBTRACT J 1)))))))) C LAMBDA BELCHECK (LTQ (IFTHENELSE (LT (SUBTRACT J 1) 1) (STRIP (BAGA A 1 (SUBTRACT J 1)))) (STRIP (BAGA A 1 (SUBTRACT J 1))) (STRIP (BAGA A 1 (SUBTRACT J 1)))) (IFTHENELSE (LTO J 1) (STRIP (BAGA A J NN)) (STRIP (BAG (ACCESS A I) (STRIP (BAGA A J (SUBTRACT J 1))))))) C LAMBDA INEQIFTHENELSE (LTQ (IFTHENELSE (LT (SUBTRACT J 1)))))) (STRIP (BAGA A 1 (SUBTRACT J 1)))) (STRIP (BAGA A 1 (SUBTRACT J 1))) (STRIP (BAGA A 1 (SUBTRACT J 1)))) (STRIP (BAGA A 1 (SUBTRACT J 1)))) (ACCESS A J) (STRIP (BAGA A (PLUS 1 I) (SUBTRACT J 1)))))) (IFTHERICSE (LTQ J 1) (STRIP (BAGA A J (SUBTRACT J 1)))))) (STRIP (BAGA A (PLUS 1 J) NN)) (STRIP (BAGA A J (SUBTRACT J 1)))))))))

Since the left side of the goal has an IF-THEN-ELSE form, it causes the rule INEQIFTHENELSE to be applied. This rule sets VERICON to be a new lower context and asserts

J-1 < I

with respect to the new VERICON. This question triggers off a demon:

5 (ASSERT (LTQ (PLUS 1 \$X) \$Y) WRT \$YERICON)

The new assertion is

 $(J-1)+1 \leq I \qquad .$

The new assertion triggers off another demon, which makes still another assertion with respect to VERICON:

6 (ACCEPT (LTG \$W \$Y) WRT \$YERICON)

This new assertion is

 $J \leq I$.

(Later in the proof, another context will be established; J-1 < I will be denied with respect to the new context.)

The THEN clause of the IF-THEN-ELSE expression must now be proved less than or equal to the right side of the goal:

7 (QUAL SIMEQUALITIES (SF (TUPLE SSMI SY SSM2)) WAT SVERICON)
This goal is attempted with respect to the new context VERICON. In other words, we are trying to prove

(STRIP (BAGA A 1 J-1))

 \leq (IF J \leq I THEN (STRIP (BAGA A J NN))

ELSE (STRIP (BAG A[I]

(STRIP (BAGA A J+1 NN))

(STRIP (BAGA A J J-1)))))

with respect to the context in which $J \le I$ has been asserted:

ELAMBDA BELCHECK (LTO (STRIP (BAGA A 1 (SUBTRACT J 1))) (
IFTHEHELEE (LTO J I) (STRIP (BAGA A J NN)) (STRIP (BAG (ACCESS A I)
(STRIP (BAGA A (PLUS I J) NN)) (STRIP (BAGA A J (SUBTRACT J 1)))))))

UNDERSTORM (BEOLETHENELSE (LTO (STRIP (BAGA A 1 (SUBTRACT J 1))))
(IFTHEMPLSE (LTO J I) (STRIP (BAGA A J NN)) (STRIP (BAG (ACCESS A I))))))))

Since the right side of the inequality is still in IF-THEN-ELSE form, the rule INEQIFTHENELSE applies again. A new context VERICON, even lower than the last, is established, and the (redundant) statement

is asserted with respect to the new context:

10 (ASSERT \$X NRT \$VERICON)

A new goal is established with respect to the new context.

The new goal is

(STRIP (BAGA A 1 J-1)) \leq (STRIP (BAGA A J NN))

LANDDA RELCHECK (LTQ (STRIP (BAGA A 1 (SUBTRACT J 1))) (STRIP (BAGA A J NN)))

LAMBDA PROOFSIMP (LTQ (STRIP (BAGA A 1 (SUBTRACT J 1))) (STRIP (BAGA A J NN)))

LAMBDA ARGSIMP (LTQ (STRIP (BAGA A 1 (SUBTRACT J 1))) (STRIP (BAGA A J NN)))

LAMBDA SIMPONE (TUPLE (STRIP (BAGA A 1 (SUBTRACT J 1))) (SIRIP (BAGA A J NN)))

The simplifier is invoked. We will omit some steps from the trace here and mention only that the rule BAGALOWERPLUS played an important part in the simplification of the second element of the tuple.

SIMPONE = (TUPLE (STRIP (BAGA A 1 (SUBTRACT J 1))) (STRIP (BAG (STRIP (BAGA A (PLUS 1 J) NN)) (ACCESS A J))))

ARGSIMP = (LTQ (STRIP (BAGA A 1 (SUBTRACT J 1))) (STRIP (BAG (STRIP (BAGA A (PLUS 1 J) NN)) (ACCESS A J))))

(GOAL \$GOALCLASSI \$X)

The simplified goal is

(STRIP (BAGA A 1 J-1))

≤ (STRIP (BAG (STRIP (BAGA A J+1 NN))

A[J]))

B3 LAMBDA RELCHECK (LTQ (STRIP (BAGA A 1 (SUBTRACT J 1)))
(STRIP (BAG (STRIP (BAGA A (PLUS 1 J) NN)) (ACCESS A J))))
94 LAMBDA INEQSTRIPBAG (LTQ (STRIP (BAGA A 1 (SUBTRACT J 1)))
(STRIP (BAG (STRIP (BAGA A (PLUS 1 J) NN)) (ACCESS A J))))

INEQSTRIPBAG breaks up the goal into two subgoals. The first of these goals is

```
(STRIP (BAGA A 1 J-1)) \leq (STRIP (BAGA A J+1 NN)) :
               (COAL SINEQUALITIES (SF (TUFLE SSU SX SSZ)))
                 LAMBDA RELCHECK (LTQ (STRIP (BAGA A 1 (SUBTRACT J 1)))
    96
    (STRIP (BAGA A (PLUS 1 J) NN)))
The rule INEQSTRIPSTRIP is applicable to this goal:
    103
                 LAMBDA INEGSTRIPSTRIP (LTG (STRIP (BAGA A 1 (SUBTRACT
Since it is known that
            (STRIP (BAGA A 1 I-1)) \leq (STRIP (BAGA A J+1 NN))
and, in this context, J \le 1, INEQSTRIPSTRIP succeeds:
The other subgoal to be proved is
               (STRIP (BAGA A 1 J-1)) \leq (STRIP (BAG A[J]))
    143
               (GOAL SINEQUALITIES (SF (TUPLE SSW (STRIP (BAG $8Y)) $$Z)))
                 LAMBDA RELCHECK (LTQ (STRIP (BAGA A 1 (SUBTRACT J 1)))
    144
    (STRIF (BAG (ACCESS A J))))
INEQSTRIPBAG applies again, splitting this goal into two subgoals, one
of which is trivial.
                LAMBDA INEQSTRIPBAG (LTQ (STRIP (BAGA A I (SUBTRACT J
   1))) (STRIP (BAG (ACCESS A J))))
                 (GOAL SINEQUALITIES (SF (TUPLE SSU SX SSZ)))
The nontrivial goal is
                      (STRIP (BAGA A 1 J-1)) \leq A \lceil J \rceil
                   LAMBDA RELCHECK (LTQ (STRIP (BAGA A I (SUBTRACT J 1)))
   147
   (ACCESS A J))
     This goal invokes the rule INEQSTRIPTRAN. We will examine the oper-
ation of this rule in detail:
```

-())))

J 1))) (ACCESS A J))

The rule finds the hypothesis

155

(STRIP (BAGA A 1 I-1)) $\leq R$

LAMBDA INEQSTRIPTRAN (LTQ (STRIP (BAGA A 1 (SUBTRACT

(EXISTS (%F (TUPLE (STRIP (BAGA %ARNAME +LOWER++UPPER))

```
It tests if this relation is appropriate:
```

```
156 (GDAL #DEDUCE (AND (LTQ $LOWER $L) (LTQ $M $UPPER) (LTQ $D $C)))
157 LAMBDA RELCHECK (AND (LTQ 1 1) (LTQ (SUBTRACT J 1) (SUBTRACT J 1))
```

The system is testing whether the array segment between 1 and I-1 includes the segment between 1 and J-1, and also whether $R \le A[J]$:

```
LAMBDA ANDSPLIT (AND (LTQ 1 1) (LTQ (SUBTRACT J 1)
153
(SUBTRACT [ 1)) (LTG R (ACCESS A J)))
                  (GOAL $GOALCLASS $X)
159
                    LAMBOA RELCHECK (LTQ 1 1)
160
                    RELCHECK = TRUE
101
                  (GOAL $GOALCLASS (AND $8Y))
163
                    LAMEDA RELCHECK (AND (LTQ (SUBTRACT J 1) (SUBTRACT
163
[ 1)) (LTQ R (ACCESS A J)))
                    LAMBDA ANDSPLIT (AND (LTQ (SUBTRACT J 1) (SUBTRACT
] [:4
1 1)) (LTQ R (ACCESS A J)))
                     (GOAL #GOALCLASS #X)
163
                      LAMBDA RELCHECK (LTQ (SUBTRACT J 1) (SUBTRACT
166
1 1))
                      RELCHECK = TRUE
167
168
                     (GOAL SGOALCLASS (AND SSY))
                      LAMBDA RELCHECK (AND (LTO R (ACCESS A J)))
160
                      LAMBDA ANDSPLIT (AND (LTQ R (ACCESS A J)))
170^{\circ}
                      (GOAL #GOALCLASS #X)
171
                        LAMBDA RELCHECK (LTQ R (ACCESS A J))
172
                        RELCHECK = TRUE
173
                      (GOAL %GOALCLASS (AND %%Y))
174
                      ANDSPLIT = (ANO)
175
                    ANDSPLIT = (AND)
176
                  ANOSPLIT = (AND)
177
```

The tests prove to be successful, and INEQSTRIPTRAN returns:

```
178 INEQSTRIPTRAN = (AND)
```

The trivial subgoal is achieved:

```
(GOAL $[NEQUALITIES ($F (TUPLE $$W (STRIP (BAG $$Y))) $$Z)))  

LAMBDA RELCHECK (LTQ (STRIP (BAGA A 1 (SUBTRACT J 1))) (STRIP (BAG)))  

RELCHECK = TRUE
```

The call to INEQSTRIPBAG from line 145 returns successfully:

```
182 INEQSTRIPBAG = TRUE
```

The call to INEQSTRIPBAG from line 94 also returns:

183 INEQSTRIPBAG = TRUE

Thus, the goal established in Line 11 has been successfully proved:

184 PROOFSIMP = TRUE

That goal was established by the rule INEQIFTHENELSE. This rule asserted $J \leq I$ with respect to a lower context and set up the goal with respect to that context. The rule now attempts to deny $J \leq I$ with respect to another context and to establish a new goal with respect to the new context.

185 (DENY \$X URT \$VERICON)

However, $J \leq I$ was also asserted with respect to a higher context in line 6. Therefore, denying $J \leq I$ contradicts this assertion, causing the denial to fail. Since the situation is contracidtory and could not arise, it is unnecessary to achieve the goal, and the call to INEQIFTHENELSE from line 9 returns successfully:

- 186 (REIURN (SUCCESS (TUPLE WITH INEQIFTHENELSE)))
 187 INCOIFTHENELSE = (SUCCESS (TUPLE WITH INEQIFTHENELSE))
- The goal established in line 7 has been achieved. This goal was set up by an earlier call to INEQIFTHENELSE line 3) with respect to a context in which J-1 < I was asserted line 4). It is now necessary to set up a new goal with respect to a new context; in this new context, J-1 < I is denied:

188 (DENY \$X WRT \$VERICON)

This denial activates a demon that denies

 $J \leq I$:

LAMBDA TRYALL (TUPLE (TUPLE PLUSEMPTY PLUSSINGLE PLUSZERO PLUSPLUS PLUSMINUS PLUSDIFFERENCE PLUSCOMBINE PLUSNUMBER) (PLUS 1 (MINUS 1)))

100 (GOAL \$GOALCLASSI \$GOALI)

191 LAMBDA PLUSMINUS (PLUS 1 I (MINUS 1))

192 PLUSMINUS = (PLUS I)

193 (GOAL \$GOALCLASSI \$GOALI)

194 LAMBDA PLUSSINGLE (PLUS I)

195 PLUSSINGLE = I

```
196 (COAL $GOALCLASSI $GOALI)
197 (RETURN $GOALI)
198 TRYALE = I
```

190 (DENY (LID SW MRTSIDE) WAT MYERICON)

The new goal

(STRIP (BAG (STRIP (BAGA A 1 I-1)

A[J]

(STRIP (BAGA A I+1 J-1))))

 \leq (IF J \leq I THEN (STRIP (BAGA A J NN))

ELSE (STRIP (BAG A[I]

(STRIP (BAGA A J+1 NN))

(STRIP (BAGA A J J-1))))

is established with respect to the new context:

INEQIFTHENELSE is invoked because the right-side of the goal is of the form IF-THEN-ELSE.

COD LAMBOA INEQUETHENELSE (LTQ (STRIP (BAG (STRIP (BAGA A 1 (SUBTRACT I 1)))) (ACCESS A J) (STRIP (BAGA A (PLUS 1 I) (SUBTRACT J 1))))) (
IFTHENMESE (LTQ J I) (STRIP (BAGA A J NN)) (STRIP (BAG (ACCESS A I) (STRIP (BAGA A (PLUS 1 J) NN)) (STRIP (BAGA A J (SUBTRACT J 1))))))

Again the rule creates two contexts: In one context $J \le I$ is asserted, and in the other $J \le I$ is denied. However, since $J \le I$ was denied in a higher context (line 199), the assertion of $J \le I$ fails; this contradictory case can safely be ignored, and attention focuses on the second context:

204 (BEN'S \$X URT \$VERICON)

The goal is established using the ELSE clause of the previous goal:

(STRIP (BAG (STRIP (BAGA A 1 I-1))

A[J]

(STRIP (BAGA A I+1 J-1))))

≤ (STRIP (BAG A[I]

(STRIP (BAGA A J+1 NN))

(STRIP (BAGA A J J-1))))

OS (GOAL \$INEQUALITIES (\$F (TUPLE \$\$H1 \$Z \$\$H2)) HRT \$VERICON)
OB LAMBDA RELCHECK (LTQ (STRIP (BAG (STRIP (BAGA A 1 (SUBTRACT L.)))) (ACCESS A J.) (STRIP (BAGA A (PLUS 1 J.) NN)) (STRIP (BAGA A J. (SUBTRACT J. 1))))))
OT LAMBDA INEQUALITIES (LTQ (STRIP (BAG (STRIP (BAGA A 1 (SUBTRACT J. 1))))))
(ACCESS A J.) (STRIP (BAGA A (PLUS 1 J.) (SUBTRACT J. 1))))) (STRIP (BAGA A 1 (SUBTRACT J. 1)))) (STRIP (BAGA A (PLUS 1 J.) NN)) (STRIP (BAGA A J. (SUBTRACT J. 1))))))

The proof from this point will only be summarized, since it is lengthy but uneventful. The goal is divided into nine subgoals by successive applications of INEQSTRIPBAG. Each of these goals turns out to be easily proved, and the proof ends successfully.

558 INCOTETHENELSE = TRUE 550 INCOTETHENELSE = TRUE 560 TRUE

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Appendix C

EXAMPLE OF HOW A VERIFICATION CONDITION IS GENERATED

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Appendix C

EXAMPLE OF HOW A VERIFICATION CONDITION IS GENERATED

For those readers unfamiliar with the Floyd-Naur method of producing verification conditions, we give below an example of its application, a complete trace of how the first condition in Section III was produced.

The program under discussion is reproduced again in Figure 5.

The path under consideration begins at point C, travels around the loop through point E, and returns again to C. We will try to prove the second conjunct at C.

This statement is

$$A \lceil 0 \rceil \le MAX, A \lceil 1 \rceil \le MAX, \ldots, A \lceil 1 \rceil \le MAX$$
 (1)

We pass this assertion backward around the loop to point E, making the corresponding substitution. The transformed assertion is then

$$A[0] \leq A[I], A[1] \leq A[I], \ldots, A[I] \leq A[I]$$
 , (2)

Since LOC does not appear explicitly in (2), the assignment LOC \leftarrow I has no effect.

To reach point E, the test

$$MAX < A[I]?$$
 (3)

must have been true. Passing the assertion back before the test gives the implication

$$\text{MAX} \, < \, \text{A[I]} \supset \text{A[O]} \, \leq \, \text{A[I]}, \, \, \text{A[I]} \, \leq \, \text{A[I]}, \, \, \ldots, \, \, \text{A[I]} \, \leq \, \text{A[I]}$$

If this implication (4) is true before the test (3), the assertion (2) will be true after the test.

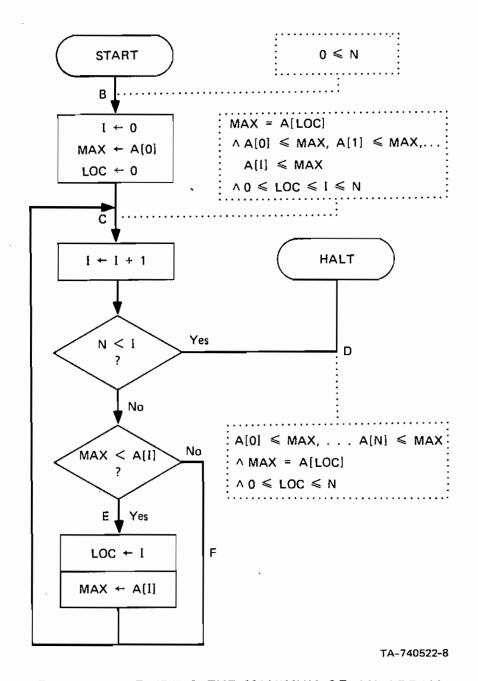


FIGURE 5 FINDING THE MAXIMUM OF AN ARRAY

To travel around the loop at all, the result of test

$$N < I? \tag{5}$$

must have been false. Passing the assertion (4) back over the test (5) gives

$$\neg (N < I) \land MAX < A[I]$$

$$\neg A[0] \le A[I], A[I] \le A[I], \dots, A[I] \le A[I] . \qquad (6)$$

Passing (6) back over the assignment statement

$$I \leftarrow I+1 \tag{7}$$

gives

$$\neg (N < I+1) \land MAX < A[I+1]$$

$$\neg A[0] \le A[I+1], A[1] \le A[I+1], \dots, A[I+1] \le A[I+1] \qquad (8)$$

This statement has been generated in such a way that if it is true when control passes through point C, then (1) will be true if control passes around the loop through point E and returns to C. If we consider this path as a straight line program with the assertion at C as both its start assertion and its halt assertion, then proving the correctness of the second conjunct (1) at C reduces to proving

$$\begin{aligned} \text{MAX} &= \text{A} \big[\text{LOC} \big] \land \\ \text{A} \big[\text{O} \big] &\leq \text{MAX}, \dots, \text{A} \big[\text{I} \big] \leq \text{MAX} \land \\ \text{O} &\leq \text{LOC} \leq \text{I} \leq \text{N} \land \\ \neg (\text{N} < \text{I}+1) \land \\ \text{MAX} &< \text{A} \big[\text{I}+1 \big] \supset \\ \text{A} \big[\text{O} \big] &\leq \text{A} \big[\text{I}+1 \big], \dots, \text{A} \big[\text{I}+1 \big] \leq \text{A} \big[\text{I}+1 \big] \end{aligned}$$

Finally, the antecedents of this implication are expressed as separate hypotheses, and the consequent is represented as a goal.

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